

User Manual Wireless Safety System Radio controlled safety module UH 6900

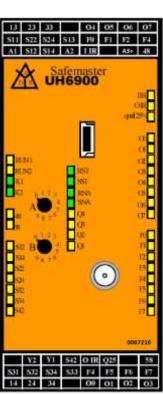


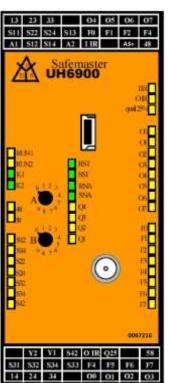
SAFEMASTER W

Enter the Wireless Safety Systems' identity code here and the used radio frequency:

Identity code:	
System code:	
Device code device 1 (target de	vice code at device 2):
Target device code device 1 (de	evice code at device 2):
Selected frequency:	Channel:
Alternative frequency:	Channel:
Alternative frequency:	Channel:

It is in the responsibility of the manufacturer of the equipment or machine to ensure its function in general. DOLD does not accept any liability for the recommendations made or implied in this manual. Also, no additional guarantee, warranty, or liability claims beyond those included in our delivery and payment terms can be derived from this.





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1 Important Notes

This manual is for your safety and for the safety of the plant operators. Read this manual carefully before you install or commission the SAFEMASTER W system and use it when working on the protected machine or equipment.

If you encounter technical problems, please contact our customer service at: +49 77 23 / 654-0; Fax: +49 77 23 / 654-356;

e-mail: dold-relays@dold.com

1.1 General safety instructions



- SAFEMASTER W must only be installed and set up by authorized and skilled personnel
- that is familiar with the correct and proper handling of safety components,
- that is familiar with the relevant regulations and standards for safety at work and accident prevention and has read and understood this user manual.
- The operator must be adequately trained and authorized to operate the machine.
- A visible emergency stop button must always be functional. In some operating modes, one of the two modules is temporarily not functional, therefore precautions must be taken to ensure that any emergency stop devices connected there are not visible.
- The operator must have a clear overview of the hazard zone at all times.

If the operator's direct view on the relevant equipment or plant parts is restricted in any way, for example the view on the access to the machine, on the drilling/milling head, etc., that is, if such areas cannot be seen from all operator positions, we recommend the installation of an additional position indicator, for example a light curtain. Then, zones with a good overview can be defined as start zones. The application can be started from within these zones only.

- The operator must be able to switch off the machine all the time While starting the machine or during operation the operator must always be able to reach the emergency stop button.
- Restarting the machine

After the machine was shut down by the safety function of the wireless SAFEMASTER W safety system, the machine must not be restarted by resetting the start button before the reason for the shut-down is detected and the problem solved.

- If more than one wireless systems are used at the same location, the different systems must be set up for different radio frequencies. There must be at least one blank channel between two active ones (for example, use channels 5, 7, 9, etc.).
- \cdot The equipment must be handled with care and be checked in regular intervals, depending on the usage and as necessary.

You, as the installer of the machine or plant, must make clear reference to these safety instructions in the relevant operating manual.

1.2 Disposal

Unserviceable devices that cannot be repaired must be disposed in accordance with the relevant country-specific waste disposal regulations.

2 Quick guide

A brief overview of the system and instructions for the initial set-up procedure in just a few steps using a simple example configuration.

2.1 Components list

In the delivery, you will receive:

- 2 UH 6900 modules,
- 2 antennas with connection adapters or connection cables,
- 1 CD with SAFEMASTER W Manager software, handbook, and license key,
- Any separate accessories (e.g. light barrier)

2.2 Configuration at delivery

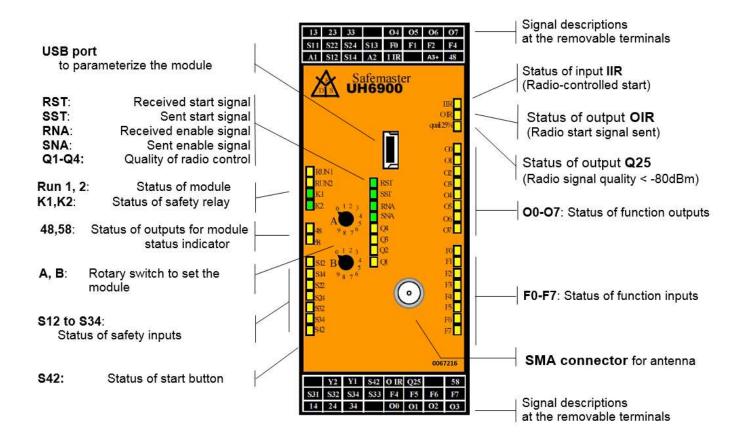
The modules are always delivered with the following configuration:

- Operating mode: Complete protected mode (rotary switch A=0, rotary switch B=0)
- Device name: not yet assigned
- Radio channel: Channel 05, 433.200 MHz (or 869.8125 MHz)
- Transmission power: 0 dBm (1 mW)

This configuration must be adjusted according to the desired system installation using the provided software or the rotary switch on the front of the module.

The identification numbers (system ID, device ID and target device ID) are already assigned and cannot be changed

2.3 Front view UH 6900



2.4 Installation of SAFEMASTER W Manger

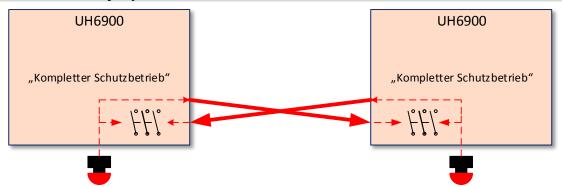
- Insert the included CD and install the SAFEMASTER W Manager on your PC (Windows operating system). The installation will start automatically, or you can also call up the setup file manually.
- A program folder will be created on your PC, and the program will be added to the start menu.
- Start the SAFEMASTER W Manager and enter the license key, which is found in a text file on the CD. Then the program will be ready for operation.

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2.5 Main operation modes

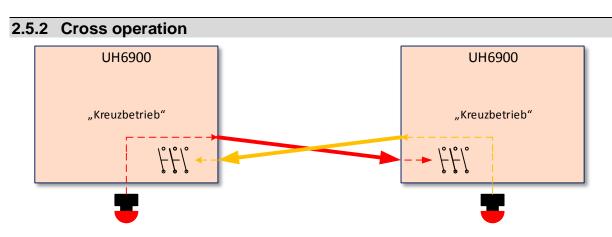
The modules always work in pairs using bidirectional safety radio transmission. In general, there are three different operating modes available.

2.5.1 Full safety operation



- One safety circuit
- Safety inputs influence the local and remote controlled safety output
- Configurable start options:
 - Manual, automatic, two-handed, additional IR enable signal

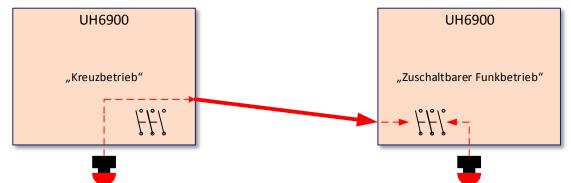
see chapter 6.4.1 Operating mode: 'Full safety operation'



- Two independent safety circuits
- Safety inputs influence the remote controlled safety output
- Configurable start options:
 - Manual, automatic, two-handed, additional IR enable signal

see chapter 6.4.2 Operating mode: 'Cross operation'



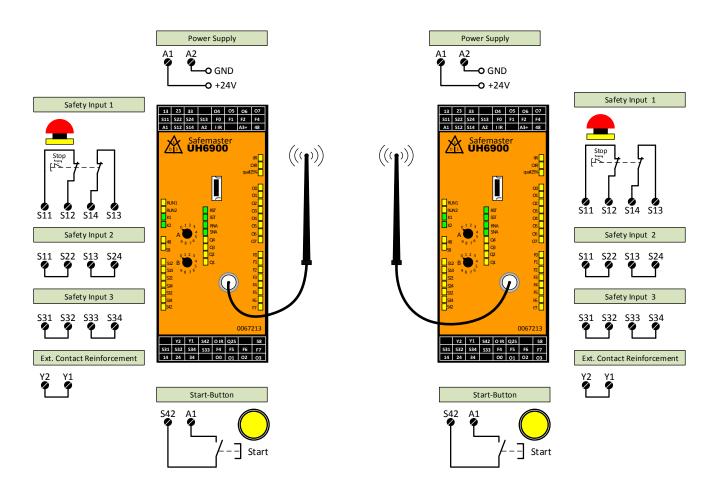


- One safety circuit
- One modulator unit and one receiver unit
- Safety inputs influence safety output on the receiver unit
- Modulator unit connectable with activated safety output
- Configurable start options:
 - Manual, automatic, two-handed, additional IR enable signal

see chapter 6.4.3 'Safety operation with optional radio control' mode of operation

2.6 Connections and oprating modes

• For the initial start-up procedure, at least the voltage supply (A1, A2), 1 safety transmitter, a start signal transmitter, the Y1, Y2 bridge and the antenna must be connected. The unused safety inputs 2 and 3 must be bridged.



• Before switching on, please check the position of the rotary switch (A=0, B=0).

• Switch the module on.

- If the setting is correct, the LEDs RUN1, RUN2, 48, and 58 will flash slowly to indicate that the module is ready for operation.
- If the setting is incorrect, the LEDs RUN1, RUN2, 48 and 58 will issue an error code (see chapter 7 "Troubleshooting")

Remark: An exact description of wiring and connection options is provided in chapter 5.5 "Terminal connections of the radio-controlled safety module" and chapter 6.3 "Wiring and connection options"

2.7 Parameterization

- Connect both UH 6900 modules at the same time or in succession to your PC via USB to complete parameterization.
- For simultaneous parameterization, the SAFEMASTER W Manager can be started twice so that you can access both devices in parallel.
- If there is already a radio connection, it is possible to access both modules with one instance of SAFEMASTER W Manager.
- Select the tab "RF settings"



• Open the tab and enter the password.

The standard password upon delivery is "0000."

File Options	
SAFEMASTER W - Manager	
Enable remote parameterization USB Device (local board)	
Local radio board is not programmable	Register unlock request
Password required Please enter administrator password	
OK Cancel	

<u>Remark:</u> It is best to change the password immediately to ensure that only authorized personnel can change the parameters.

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• After opening the tab, you can change the device name, frequency channel, and transmission power.

2.7.1 Frequency channel

The modules can only communicate with one another if they are both set to the same channel, if they emit sufficient transmission power, and if they are not disrupted by other devices transmitting on the same channel.

- Therefore, it is necessary to prepare a frequency plan for the entire system in order to avoid mutual disturbances by devices.
- Channel 5 is set at delivery. Change this channel according to your specifications. Permitted values are 1..64 in the 433 MHz range and 1..12 in the 869 MHz range

Radioboerd Modul (UH6900) -	local board ID 1			
File Option:				
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2.7.2 Integrated spectrum analyzer

You can use the integrated frequency analyzer to quickly check the set channels and frequencies in your system environment. It will go through all channels in the frequency range and measure the received power. This allows you to very easily determine which channels are already in use.

However, this measurement in no way replaces an exact frequency plan of your system.

- Select the spectrum analyzer by switching to the "Spectrum" tab.
- Turn on the spectrum analysis. It will take approximately 50 seconds to go through all 64 channels.

The example shows one transmitter on channel 5 and another on channel 10.

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2.7.3 Further adjustments

The transmission power and device name do not have to be changed for initial start-up

2.7.4 Programming

If the channel was changed in the prvious step, this setting must be permanently saved in the device. The programmer button will now appear blue. The status window will indicate that the programming was successful.

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Target ID verified	2	Target ID verified
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	Change password	
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2.8 Power on and standby test

After successful parameterization and after switching on the modules once again, the LEDs RUN1, RUN2, 48, and 58 should flash slowly to indicate they are ready for operation.

If there is an error, these LEDs will show different flashing codes.

see chapter 7.2 "Status and error codes"

Press the start button on one of the two devices

- → The safety relays on both devices activate
- Press the emergency stop button on one of the two devices
 - → The safety relays on both devices deactivate

For further controlling, you can check the current status of the transmission path using the SAFEMASTER W Manager.

• If the connection was established successfully, both modules will be displayed in the window with the set parameters.

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3 Introduction of the system

SAFEMASTER W – is an innovative wireless safety system to protect man and machine. A feature of the Wireless Safety System is its **safety-oriented bi-directional radio transmission** for transmitting signals between two wireless safety modules so that the two separate safety devices, each of them installed on a different machine part that is not connected to the other by wires (for example, moving machine parts), work together as one system. In addition, the systems allows the configuration of different operating modes.

SAFEMASTER W **definitely solves** the problem of wear on trailing cables without the necessity to compromise **safety and response time**.

3.1 Directives, standards, and certification

The Wireless Safety System SAFEMASTER W meets all the safety requirements of the currently valid directives and standards.

- Machine directive 2006/42/EC
- IEC/EN ISO 13 849-1: Category 4, Performance Level "e"
- IEC/EN 61 508: SIL Claim Limit SIL 3
- IEC/EN 61 511: SIL Claim Limit SIL 3
- IEC/EN 62 061: Safety Integrity Level SIL CL 3
- DIN EN 574: Safety of machinery Two-hand control devices –

Furthermore, the Wireless Safety System SAFEMASTER W is in accordance with the standard

• DIN EN 300 220

Electromagnetic compatibility and Radio spectrum Matters (ERM) – Short Range Devices (SRD) – Radio equipment to be used in the 25 MHz to 1 000 MHz frequency range with power levels ranging up to 500 mW



Please note: Validation according to DIN EN ISO 13849-2 is always required for the complete system.

3.2 Applications, intended use

Typical applications of SAFEMASTER W are:

- Hazard areas where protective equipment is necessary for the safety of persons but where wiring is impossible or not reasonable, for example in applications with extremely wide-spread, extensive hazard zones;
- Mobile and stationary plants and equipment, for example large machines, assembly halls and scaffolds, conveyor belts, high-rack warehouses, warehouses, forklifts, etc.

The UH 6900 radio-controlled safety modules are intended for the wireless remote control of machines and plant parts that used to be controlled by cable. Their usage is only restricted by valid safety instructions that prohibit, for example, staying under suspended loads.

The radio transmission range is approx. 800 m in the free field and approx. 150 m in an industrial environment.

3.3 Design

The main components of the safety system are the two radio-controlled safety modules.

Each UH 6900 radio-controlled safety module is installed in a switch cabinet or on a mobile device and is operated with a plug-in or external antenna. It detects the signals of up to three wired safety elements plus the signals from the related second active radio-controlled safety module that are sent through a safe radio transmission. Safety-relevant switching commands are switched by relay outputs, non-safety-relevant control signals through semiconductor outputs.

In addition to the up to three 2-channel safety devices, there are 8 non-safety function inputs (DC 24 V) and 8 non-safety function outputs (semiconductor outputs, DC 24 V), whose states are transmitted or received through the safe radio transmission. LEDs inform about the states of all inputs and outputs and indicate the current state of the internal radio-controlled safety module.

The current state of the UH 6900 radio-controlled safety module is also indicated by two non-safety-relevant semiconductor outputs.

In addition, a non-contact sender and a non-contact receiver (for example, light curtain or infrared sender and receiver) may be connected to force the system to start from a specific location via radio.

3.4 Functions

The modules allows the selection of three different main operating modes by a rotary switch.

- Full safety operation
- Cross-operation
- <u>Safety operation with optional radio control</u>

For each of these operating modes, the start mode (auto start, manual start, or start by twohand control) of the module can also be selected by the rotary switch.

The individual operating modes are described in more detail in section 6.4 Setup and commissioning of the UH 6900 radio-controlled safety module.

The UH 6900 radio-controlled safety module is equipped with a DC 24 V semiconductor output **OIR** that reproduces the start signal to enable the safety relay.

As an additional accident prevention measure, all of the above-mentioned operating modes can be set to detect this additional start signal from the opposite side via the DC 24 V **IIR** input. This allows, for example, the determination of start areas by the use of a light curtain or infra-red sender and receiver. **Only from these start areas, the application can be started via radio.** For a successful start, the system then requires a start signal at the **IIR** input in addition to the start signal via the safety radio transmission.

4 System description

4.1 Design and functions of the UH 6900 radio-controlled safety module

4.1.1 Main features of the UH 6900 radio-controlled safety module

- Depending on the operating mode, to connect:
 - Emergency-stop push-button (2-channel), safety gate, LC (non-contact safety system, for example light curtain) of the type 4 in accordance with EN 61 496 or the two-hand type IIIA in accordance with DIN EN 574.
 - 1 start button
 - Changeover switch (2-channel) to indicate radio use in the 'Safety operation with optional radio control' operating mode
- For two-way communication via radio:
 - Safety shut-down commands
 - Signals from 8 non-safety-relevant DC 24 V inputs at 8 non-safety-relevant DC 24 V semiconductor outputs
- Broken wire and short circuit detection with fault indication
- Semiconductor output to indicate poor or no radio control
- 2 semiconductor outputs for status indication
- LEDs to indicate status of module
- LEDs to indicate status of all inputs and outputs
- LEDs to indicate the radio transmission and its quality
- 45 mm in width
- Compact device easy to install
- Mounting on profile DIN rail
- Removable screw terminal blocks
- Functions that can be selected by rotary switches:
 - 'Full safety operation' with different start modes (two-hand type IIIA and/or manual start, auto start)
 - 'Cross-operation' with different start modes (two-hand type IIIA and/or manual start, auto start)
 - 'Safety operation with optional radio control' with different start modes (manual start on S42, manual start via radio, or auto start)
 - Valid for all operating modes: Radio start function via radio with or without detection of an additional start signal at the IIR input.
- Frequency range 433 MHz or 869 MHz (license-free radio frequencies)
- Radio channel, transmitter power, and module name can be set by means of a parameterization software
- Status indicator for the devices connected via radio, by means of the parameterization software including status of radio transmission quality

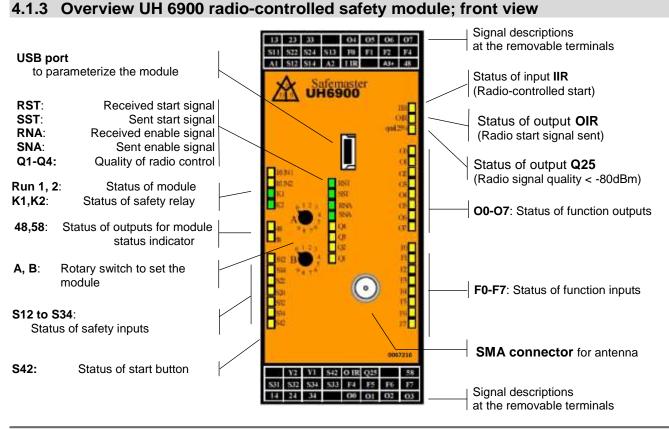
4.1.2 Inputs and outputs

Inputs

- 3 two-channel safety inputs DC 24 V
- 1 DC 24 V input for start button
- 1 feedback circuit to monitor external relays
- 1 DC 24 V input that can be used as start signal in addition to the start signal received via radio.
- 8 non-safety-relevant DC 24 V functional inputs, the status of which is sent to the opposite side.

Outputs

- 3 safety-relevant NO contacts or
- 2 safety-relevant NO contacts + 1 NC contact (can only be used as an indicator contact)
 1 DC 24 V semiconductor output that reproduces the start signal sent via radio as an
- additional start signal for the release of the safety relay on the opposite side
- 8 non-safety-relevant DC 24 V semiconductor outputs that are controlled by the opposite side
- 2 DC 24 V semiconductor outputs to display the status of the radio-controlled safety module
- 1 non-safety-relevant DC 24 V semiconductor output to indicate poor or no radio control



4.1.4 Detection of safety elements

If the radio-controlled safety module is switched off through a hard-wired safety element (for example, the emergency stop push-button) the following requirements must be met for a restart:

Both control signals of the operated 2-channel safety element must have been switched off simultaneously (open contact). Restart (closed contact) of the two signals must take place within 3 s (in case of two-hand, 500 ms).

If the control signals of the safety elements are already applied when power is switched on, the safety elements meet the start requirements.

Any specifics regarding the detection of the safety signals based on the selected modes of operation are mentioned in the descriptions of the operating modes.

4.1.5 Start options

4.1.5.1 Manual start and reset

The start button to be connected to terminal S42 is used for the manual start and also to reset the radio-controlled safety module. The maximum activation time for the start buttons is 3 sec. If the button is pressed longer than 3 sec., the unit will not start. A start button must not be pressed when power is being applied to the UH 6900 radio-controlled safety module.

4.1.5.2 Auto start

The safety inputs S12-S14, S22-S24 and S32-S34 can be set up for automatic start (see operating modes). This means that the radio-controlled safety module UH 6900 enables the safety relays as soon as the safety function is active again (for example, the safety gate is closed again).

4.1.5.3 Two-hand

In some operating modes, the safety input on S12-S14 can be used for a two-hand control of the type III A.

In this case, the following steps - in the order prescribed below - must be carried out each time a safety relay is disabled:

- The two-hand buttons must be released.
- All other safety inputs must be closed again and (if they are set to manual start) reset.
- Only now, the safety relays can be enabled again by the two-hand control.

If this order is not observed the safety relays will not start.

4.1.5.4 Start via radio



Starting the plant or machine must be limited to a specific start zone with a good overview of the hazard zone.

If one of the radio-controlled safety modules is installed on a mobile device (for example a fork-lift truck) and if it is intended that starting via radio is possible from that device as well, enabling start through the **IIR** input is the best option. For example, the output of an infra-red receiver can be connected to this input when the related infra-red sender is controlled by the **OIR** output of the other radio-controlled safety module. This forces the operator to go to the defined start zone.

When this option is selected the receiver of the start signal waits for 2 conditions to be fulfilled before the safety relay is enabled:

- 1. Receipt of a valid start command sequence.
- 2. Detection of a start signal at the IIR input that fetches to the received start sequence.

) If this start signal IIR is used with a two-hand control in the safety system, this option must be activated at the module, with the connected two-hand control buttons.

4.1.6 Semiconductor outputs

Except for the contact-type safety outputs, all outputs are non-safety-related DC 24 V semiconductor outputs.

- Outputs 48 and 58 provide information about the current state of the safety module.
- Output Q25 is set if the signal quality falls below -80 dBm or if no signal is received at all.
- Output OIR is set as long as the module sends a radio start command to the second radiocontrolled safety module that belongs to the SAFEMASTER W system.
- The function outputs O0 to O7 are controlled via radio through the function outputs F0 to F7 of the other radio-controlled safety module that belongs to the system. In order to safely switch off all function outputs, their DC 24 V power supply is connected to a separate terminal (A3+).

4.1.7 Assignment of function inputs to semiconductor outputs

The function inputs of a module are directly (one-to-one) assigned to the function outputs of the other module. This means that, for example, the F1 function input controls the O1 function output of the opposite side.

4.1.8 Identity code

Before it is dispatched, each radio-controlled safety module receives a unique and fixed identity code (comprising a system code and a device code) by which it is permanently assigned to its related radio-controlled safety module (same system code and target device code).

These settings cannot be changed by the user.

A SAFEMASTER W system will only function if the system codes of both radio-controlled safety modules match and the device code of one module is stored as the target device code of the other module. The radio-controlled safety modules check any incoming commands for their own identity codes and the identity codes of the respective sender module. Only those commands are carried out by a radio-controlled safety module that can be properly assigned.



When you order a system, keep in mind that any SAFEMASTER W radio-controlled safety system that is realized with UH 6900 radio-controlled safety modules will always

consist of two units whose identity codes have been paired at DOLD already.

The customer can neither determine their identity codes nor change them.

4.1.9 Receiver antenna

The radio connection between the two radio-controlled safety modules of a SAFEMASTER W system is made via an antenna that may be attached directly to the front of the radio-controlled safety module. If the unit is installed at a location that is not suited for radio control (for example in a metal cabinet) the antenna can be installed at a more favorable place and connected via a special shielded coaxial cable.

4.1.10 Radio frequency

The radio-controlled safety modules communicate via a free radio frequency in the 433 MHz or 869 MHz frequency band. The frequency can be set by selecting the channels using the parameterization software.

If more than one SAFEMASTER W systems are used at the same location, the different systems must be set up for different radio frequencies. The used frequency channels must not be neighbouring channels, there must always be an unused one in between.

The frequency can be set by the user (see Section 6.2.2.1 Set the radio frequency)

4.1.11 Transmitter power

To adjust the device's working range to the required conditions, the transmitter power can be set with the parameterization software, depending on the selected frequency channel and frequency band in a range between -40 dBm (0.0001 mW) and a maximum of 10 dBm (10 mW).

5 Installation and connection

5.1 Important notes on installation and connection



 Before you turn on the radio-controlled safety module for the first time, the required operating mode must be set (see <u>5.4.1 Setup and commissioning of the radiocontrolled safety module</u>)

• A visible emergency stop push-button must always be functional.

Because the safety functions on one of the two modules are temporarily not functional in some operating modes, precautions must be taken to ensure that any emergency stop devices connected to it are not visible during this time.

• This device is not suitable for use in places where children might be present.



Provide for potential equalization before making any adjustments or cabel connection.

It has shown that a successful installation depends on the following factors:

- Location of radio-controlled safety module and the antenna
- Connection and positioning of the radio-controlled start device (for example, light curtain, or infra-red sender and receiver)
- Connection of safety elements
- Careful and proper wiring
- Protection of power supply
- Min. and max. switching current of the different outputs
- Disturbance protection

5.2 Wiring

Do not install cables of different classes in parallel. Maintain a minimum distance (20 cm) between the different cable classes:

Class 1: Radio, antenna wires (antenna extension wires)

Class 2: Electric circuit for supply of the different enclosures

Class 3: Power control for motors, controls, etc.

Ideally, each cable class is installed in its own cable duct. If only one cable duct is available, the different classes of cables should be installed at the maximum possible distance from each other.



The electrical connection of the power supply must be installed in a way that with deactivation of the main power switch the radio-controlled safety module is deactivated as well.

If the power supply circuit of industrial installation is not equipped with an all-pole power circuit-switch, a suitable separator must be available as a part of the electrical system of the building.

Protection against contact of the connected elements and insulation of the supply lines must be designed for the maximum voltage applied to the device.

5.3 Protection of power supply

Protection against overcurrent resulting from overvoltage (EN 60204-1, Sec. 7.2).

The power supply of the UH 6900 radio-controlled safety module is protected by means of an internal PTC.

5.4 Positioning of the radio-controlled safety module and the antenna

5.4.1 Positioning of the radio-controlled safety module

The radio-controlled safety module must be installed as close as possible to the machine to be controlled, preferably inside the control cabinet. It must be protected against shocks and weather influences.

5.4.2 Distribution of radio signals

Radio signals are electro-magnetic waves that are attenuated on their way from the sender to the receiver. Their transmitter field intensity decreases inversely proportional to the quadrature of the distance between sender and receiver. In addition, the signals are attenuated further if they need to penetrate other materials than air (e.g. walls, objects, or persons).

Examples for the attenuation of the signals through different materials:

Penetration
90 100 %
65 95 %
10 90 %
0 10 %

In addition, it should be noted that the material strength is increased by the same proportion when the signal must penetrate the material diagonally. It should therefore be ensured that the material is penetrated in an angle that is as close as possible to the right angle.

5.4.3 Positioning of antenna

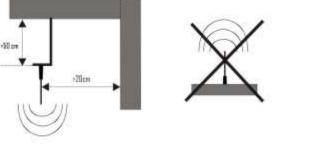
The antenna must be installed outside the switch cabinet and in the maximum possible distance to class 3 cables and power equipment (power supplies, motors, inverters) and, at the same time, in an area that is suitable for receiving radio signals. If necessary, an antenna extension cable should be used. The antenna extension cable must not be bent because this would result in an additional attenuation of the radio signal.

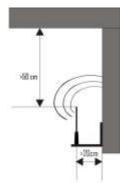
The antenna should be positioned as high as possible in the room, centred above the area that is to be controlled and in which the antenna of the receiver moves.

Between the antennas, there should not be any materials that can have a shielding effect. Ideally, the other antenna should be visible from the position of the first one.

The following minimum distances apply for the antenna: 0.5m to ceilings and 0.2 m to walls!







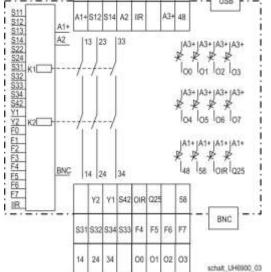
M_Antenne

Radio systems can receive interfering signals from other systems and can also interfere with other systems. The system, and in particular its antenna, is to be set up in a way that systems do not interfere with each other, the same applies to the used frequency channel.

- The antennas of two radio systems using the same frequency band should not be closer than the minimum distance of 3 m.
- The antennas of two systems using different frequency bands (e.g. GSM or WLAN) should have a minimum distance of 50 cm.

5.5 Terminal connections of the radio-controlled safety module

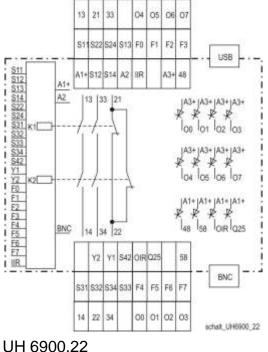




13 23 33

S11522 S24 S13

UH 6900.03



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			1
Terminal	Description	Terminal	Description
A1+	DC 24 V supply voltage for	Terminal Y1/Y2 13/14 23/24 or 21/22 33/34 IIR OIR Q25 F0 to F7	Input for feedback loop of external
	radio-controlled safety module		contact reinforcement
A2	Common earth	13/14	1st safety output, safety NO contact
	Non-safety DC 24 V	23/24	2nd safety output, safety NO
48/58	semiconductor outputs: State of	or	contact
	radio-controlled safety module	21/22	Monitoring output (NC contact)
S11, S31	Test outputs for short circuit detection of the safety inputs Sx2	33/34	3rd safety output, safety NO contact
S13, S33	Test outputs for short circuit detection of the safety inputs Sx4	IIR	Input for enabling the received start signal
S12, S14	Inputs of the two-channel safety input 1	OIR	Output with image of sent start signal
S22, S24	Inputs of the two-channel safety input 2	Q25	Output for input signal quality < -80 dBm
S32, S34	Inputs of the two-channel safety input 3	F0 to F7	Non-safety function inputs
S42	Input for hard-wired start button	O0 to O7	Non-safety DC 24 V function outputs
		A3+	DC 24 V power supply of the function outputs = O0 to O7

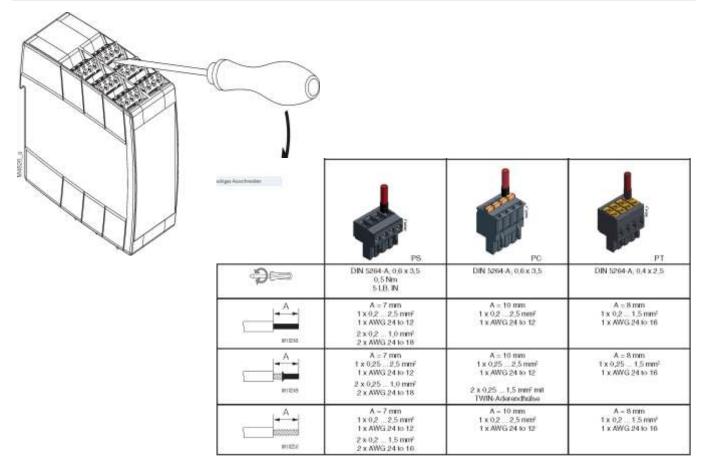
5.6 Connection of safety elements



The safety elements must always be connected as shown in the connection examples.

When connecting safety elements with semiconductor outputs (e.g. LC type 4 according to EN 61496) the unit will not detect any short circuit between the signals. The short circuit must then be detected by the safety element itself.

5.7 Installation / removal of the PS / PC terminals



5.8 Minimum and maximum output currents

Make sure that the minimum and maximum output currents stated under <u>Technical data</u> are not underrun or exceeded. If necessary, install additional power or interface relays (e.g. an amplifying relay in the switch cabinet to control power).

5.9 Disturbance protection

If inductive loads are connected to relay outputs (contactor coils, electrovalves or electric brakes) make sure to provide the right protection devices (such as capacitors, RC circuits, diodes, etc.) directly at the controlled elements and connect them with the shortest possible wiring.

6 Commissioning (operating manual)

6.1 General instructions for commissioning

- Before you turn on the UH 6900 radio-controlled safety module for the first time, it must be set for the required operating mode (see Section <u>Setup and commissioning of the radio-controlled safety module</u>).
- Check for a proper matching of identity codes and radio channels of both radio-controlled safety modules of the SAFEMASTER W system.
- Check if the selected radio channel corresponds to the frequency plan set up for the location.
- Determine the range of the radio signals during operation in the entire work area and take into consideration interferences with other radio equipment at the location.
- Check if the function inputs of the radio-controlled safety module are correctly assigned to the function outputs of the other radio-controlled safety module. During these checks, make sure that the outputs O0 to O7 on both radio-controlled safety modules remain disabled before enabling the radio transmission.
- When you start the system through the IIR input, check if the start detection is limited to the area defined for this application. It must be excluded that the system can be started from outside the defined start area.

6.1.1 Close-by machines equipped with SAFEMASTER W systems

If several machines are equipped with SAFEMASTER W systems that are operated close-by (for example, in a workshop) - and especially if one radio-controlled safety module is installed on a mobile device - each individual machine part must be marked clearly so that the machine operators can identify to which machine they belong without any doubt. For this, the system code of the SAFEMASTER W system could be attached to the relevant machine parts so that it is clearly visible and can be read from further away.

6.2 Configuration at shipment

The modules are always shipped with the default settings listed below: We recommend changing the frequency channel immediately upon receipt to prevent inadvertent Infol influences in case of spare part deliveries or close-by new plants or machines. Enter these new settings on page 1 of this manual.

- Radio channel: Channel 05, 433.200 MHz (or 869.8125 MHz)
- 0 dBm (1 mW) Transmitter power:
- Identity number: The radio-controlled safety modules are shipped in pairs and are • permanently assigned to each other by a unique identity code (unchangeable system code and device code 001 and 002).
- Rotary switch A = 0, rotary switch B = 0: Operating mode:
 - 'Full safety operation', 3 x manual start.
- One-to-one assignment of the function inputs to the function outputs on the opposite side (F0 \rightarrow O0,... F7 \rightarrow O7)

6.2.1 Display of identity code

The module's own identity code and the identity code of the assigned radio-controlled safety module are clearly marked on the device enclosure. They are also displayed by the supplied parameterization software in three groups of figures:

- The unique common system code of the two modules of a SAFEMASTER W system •
- The device code
- The target device code

Both radio-controlled safety modules of a SAFEMASTER W system must be matched to each other by these three groups of figures.

6.2.2 Selection and setting of the radio frequency

The 64 radio channels in the 433 MHz frequency band and the 12 radio channels in the 869 MHz frequency band of the UH 6900 radio-controlled safety module provide a broad selection of available channels.

6.2.2.1 Set the radio frequency

The modules' radio frequency is set by using the supplied parameterization software, via the USB interface.

Both radio-controlled safety modules of a SAFEMASTER W system must be set to the same frequency channel.

Close-by SAFEMASTER W systems must be set to different frequency channels.

For a good operation quality, it is necessary to make sure that the selected frequency channel is not used by any other equipment in the working area.



If several SAFEMASTER W systems are operated at the same location, it is necessary to have at least one free channel between 2 active ones (e.g. 5, 7, 9). Info It is recommended to set up a frequency plan listing all the active frequencies of a system and the controlled equipment.

Which frequencies are used in a working area can be easily detected by means of a costefficient standard frequency scanner.

It is recommended to select at least two spare frequencies for each application in order to quickly change to another frequency in the case of an interference without having to measure the frequency first.

Availability of the selected free frequencies must be checked in regular intervals.

6.2.2.2 Set the transmitter power:

The modules' transmitter power is set by using the supplied parameterization software, via the USB interface.

Depending on the frequency band, it can be set in the range from -40 dBm (0.0001 mW) to a maximum of 10 dBm (10 mW).

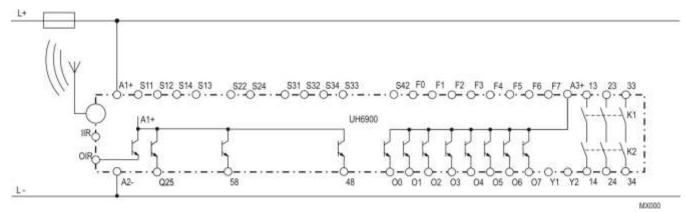


In the 433 MHz frequency band, the full range of 64 frequency channels can only be set for a transmitter power of up to 0 dBm (1 mW). With a power of > 0 dBm (1 mW to 10 mW), only the channels 40 to 64 are available.

In the 869 MHz frequency band, the transmitter power can only be set to a maximum of 7 dBm (5 mW).

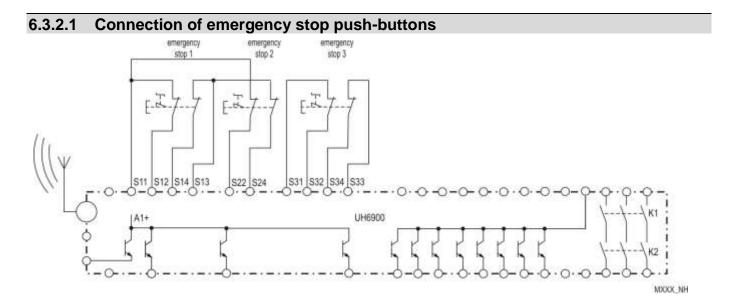
6.3 Wiring and connection options

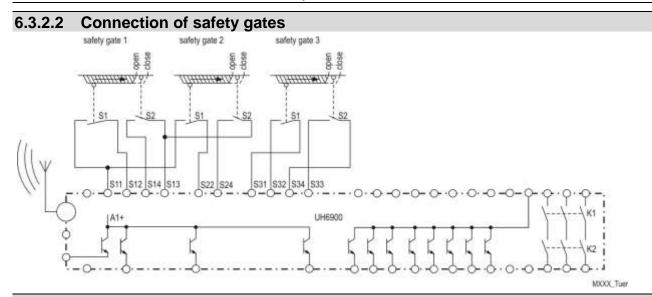
6.3.1 Connection of power supply

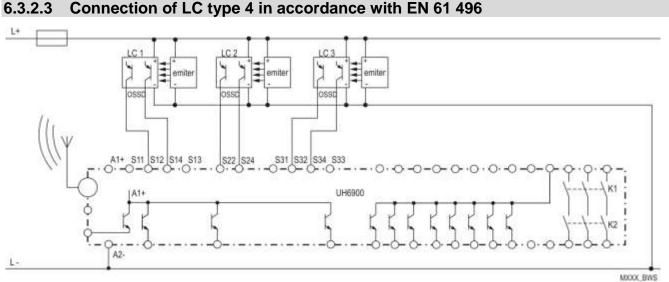


6.3.2 Connection of safety elements

- Note: If used, the two-hand control must always be connected to the terminals S11 to S14.
- Note: In the "Full safety operation" mode of operation, a maximum of one two-hand control units may be available in the system.
- Note: Emergency stop, safety gates, and LC can be connected in any combination, also together with a two-hand control.
- Note: If a safety input is not required, jumpers must be connected to the respective terminals instead of the NC contacts for an emergency stop push-button.







LC: non-contact protective equipment

6.3.2.3.1 Calculation of the safety distance of an LC connected to a UH 6900

Any LCs connected to the UH 6900 radio-controlled safety module must be installed at a distance that corresponds to or exceeds the minimum safety distance S so that it is impossible to reach a dangerous spot before the machine has stopped a dangerous movement.

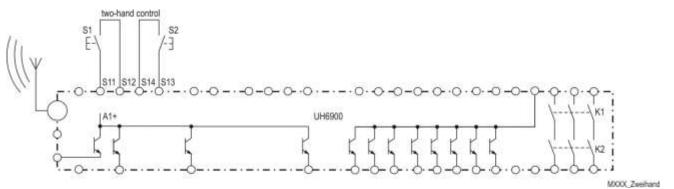
Note:

- The European EN ISO 13855:2010 standard (Safety of machines Positioning of protective equipment with respect to the approach speeds of parts of the human body) provides the information necessary for the calculation of the correct safety distance.
- Carefully read the installation instructions for each individual LC to obtain knowledge of specific information regarding their positioning.
- Always keep in mind that the total response time of the system depends on the following factors:

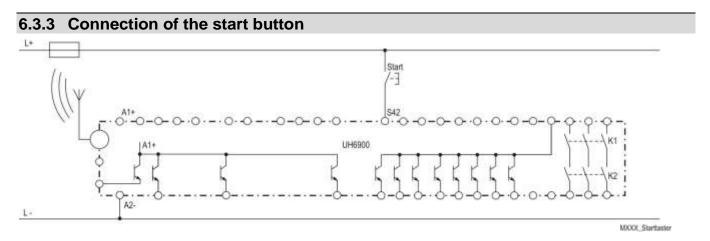
Total response time = response time of LC + response time of SAFEMASTER W system + response time of machine (in seconds).

• Note that the response time of the SAFEMASTER W system is increased if the stop signal must be transmitted to the machine via radio.

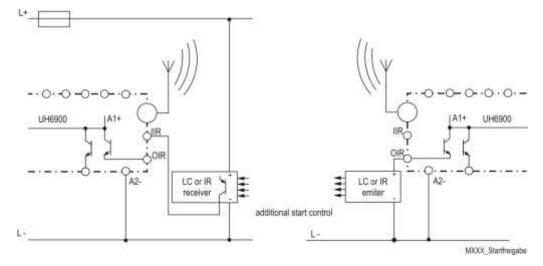
6.3.2.4 Connection of two-hand control IIIA in accordance with DIN EN 574



- In the "Full safety operation" mode of operation, only one two-hand control unit may be available in the system.
- A two-hand control must always be connected to the terminals S11 to S14.



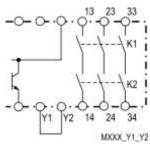
6.3.4 Connection of an additional start control over IR or LC



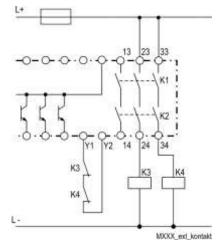
Only <u>one</u> device in a system can be set to the operating mode 'Detection of the radio start signal together with the start signal on the IIR terminal'.

The additional start control belongs to that device at which the IR/LC receiver is connected.

6.3.5 Operation with or without external contact reinforcement

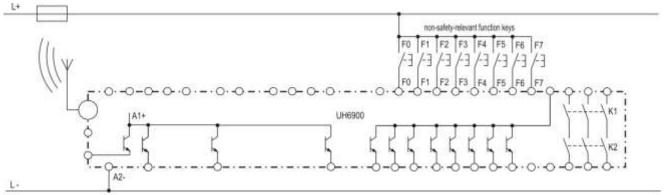


No external contact reinforcement

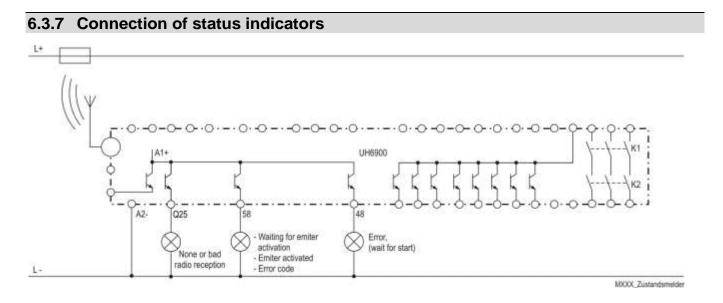


External contact reinforcement

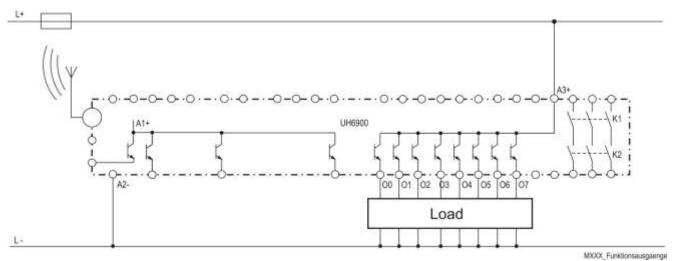
6.3.6 Connection of non-safety-relevant function inputs



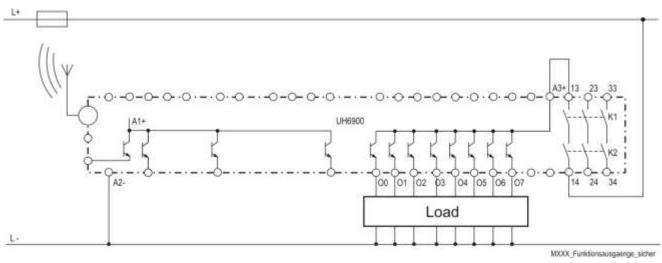
MXXX_Funktionseingsenge



6.3.8 Connection of non-safety-relevant function outputs



Without safe disconnection of function outputs



With safe disconnection of function outputs

6.4 Setup and commissioning of the UH 6900 radio-controlled safety module



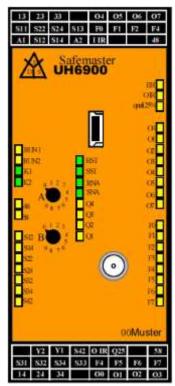
Adjustments must only be carried out by trained staff while the unit is disconnected from power.

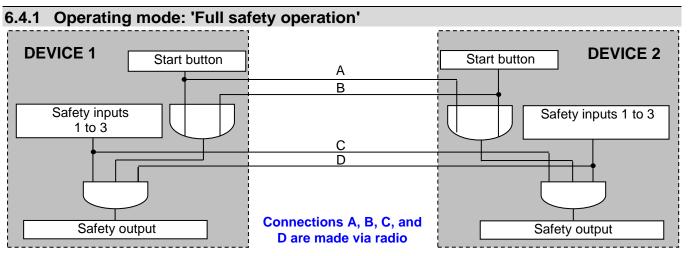


Provide for potential equalization before making any adjustments.

The operating modes of the UH 6900 radio-controlled safety module listed below are selected using the rotary switches A and B.

- 'Full safety operation' with the sub-functions:
 - 3 x manual start
 - 2 x manual start + 1 x auto start
 - 1 x manual start + 2 x auto start
 - 3 x auto start
 - 1 x two-hand type III A + 2 x manual start
 - 1 x two-hand type III A + 1 x manual start + 1 x auto start
 - 1 x two-hand type III A + 2 x auto start
- 'Cross-operation' with the sub-functions:
 - 3 x manual start
 - 2 x manual start + 1 x auto start
 - 1 x manual start + 2 x auto start
 - 3 x auto start
 - 1 x two-hand type III A + 2 x manual start
 - 1 x two-hand type III A + 1 x manual start + 1 x auto start
 - 1 x two-hand type III A + 2 x auto start
- 'Safety operation with optional radio control'full safety operation with the sub-functions:
 - 2 x manual start
 - 2 x auto start
 - With radio control on, reset of remote deactivation through sender
 - With radio control on, reset of remote deactivation through start button on S24 after restarting the sender
 - With radio control on, reset of all deactivation functions through sender The maximum time allowed for activating the control unit can be set between 5 s and 30 s.
- Valid for all operating modes: Radio start function via radio with or without detection of the additional start signal at the IIR input (LC or IR)





In 'Full safety operation' mode, always two radio-controlled safety modules work together which are both set to this mode of operation.

Both modules are permanently connected via radio. The safety relays on both sides are only enabled if all of the conditions for enabling the safety output are fulfilled.

As soon as any of the safety inputs becomes inactive on either one of the modules or if the radio transmission is disconnected, the safety relays of both modules drop out.

6.4.1.1 Set-up of safety inputs and start mode

		FULL SAFETY OPERATION	
Rotary switch B		Protective equipm	Both devices must be set to one of these operating modes.) nent on S11-S14, S22-S24, S31-S34, and S11-S14, S22-S24, S31-"34 on the posite side will always influence the safety relays on both sides.
	0 to 4	Detection of radio	start signal only
Α	5 to 9	Detection of the	radio start signal together with the start signal on the IIR terminal.
0	0,5	S11-S14, S22-S24,	S31-S34: Manual start with start button on S42 or through the start signal on the opposite side.
	1,6		Manual start with start button on S42 or through the start signal on the opposite side. Auto start
	2,7	S11-S14: S22-S24, S31-S34:	Manual start with start button on S42 or through the start signal on the opposite side. Auto start
	3,8	S11-S14, S22-S24,	S31-S34: with auto start
	4,9		Two-hand control type III A Manual start with start button on S42 or through the start signal on the opposite side.
1.	0,5	S11-S14: S22-S24: S31-S34:	Two-hand control type III A Manual start with start button on S42 or through the start signal on the opposite side. Auto start
	1,6	S11-S14: S22-S24, S31-S34:	Two-hand control type III A Auto start
	R	est of the positions	s (2, 3, 4, 7, 8, 9) of the rotary switch B are not assigned (system error 5)

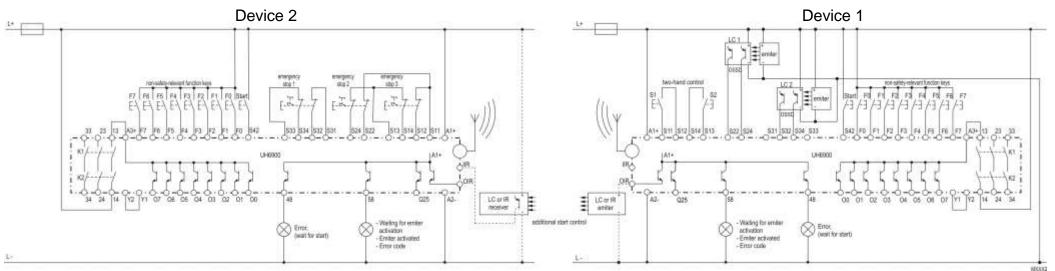


- Only **<u>one</u>** device in a system can be set to the operating mode 'Detection of the radio start signal together with the start signal on the **IIR** terminal'.
- Only <u>one</u> device in a system can be set to the operating mode 'two-hand control'.

In the operating modes with two-hand control, both push-buttons of the two-hand control must be released if another safety element of the radio-controlled safety system responds.

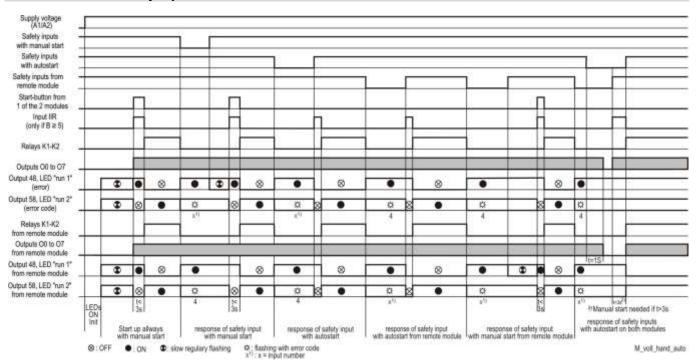
Only after all other safety elements of both modules are free again and reset, if necessary, the safety relays on both sides can be enabled again with the two-hand control.

6.4.1.2 Application examples

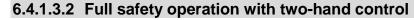


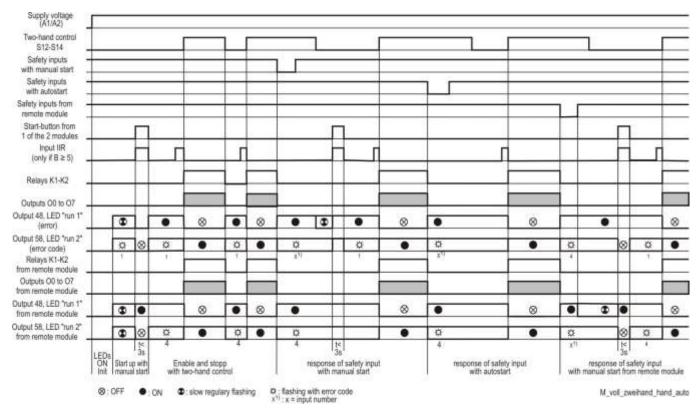
- The safety inputs on S11-S14, S22-S24, and S31-S34 can all be equipped with a two-channel push-button or with a LC of the type 4 in accordance with EN 61 496.
- The two-hand push-buttons are always connected to S11-S14 and there must be only **one** device in the system equipped with a two-hand control.
- Only <u>one</u> device in a system can be set to the operating mode 'Detection of the radio start signal together with the start signal on the **IIR** terminal'.

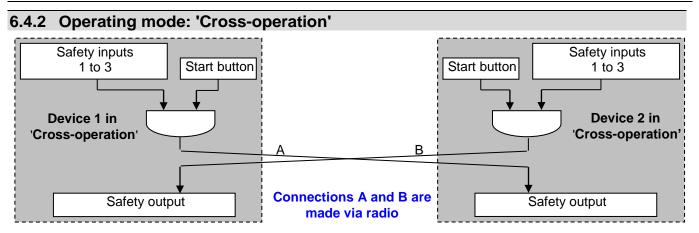
6.4.1.3 Function diagrams



6.4.1.3.1 Full safety operation without two-hand control





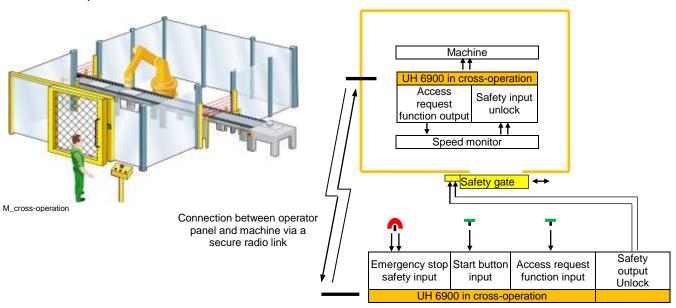


The two radio-controlled safety modules represent two independent systems where the inputs, including the start button input, on one side only control the safety relays and function outputs on the other side.



Emergency stop actuators must shut down the entire plant or machine. Therefore, this operating mode is suitable for emergency stop functions only if the safety outputs of the device, to which the emergency stop actuator is connected, are not used to stop dangerous movements.

Note: This operating mode can be used, for example, to request a speed reduction for a machine from a greater distance via radio and to allow access only after the slower speed has been confirmed via radio.



Example for a cross-operation application

Note: A UH 6900 radio-controlled safety module that is set to the 'cross-operation' mode of operation can also be used to control a UH 6900 radio-controlled safety module that is set to the operating mode 'Safety operation with optional radio control'

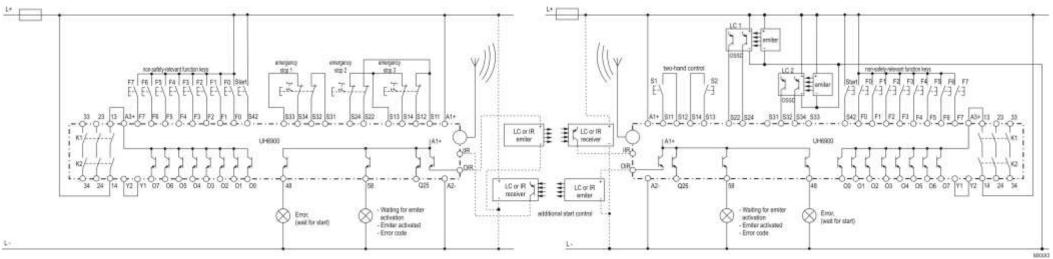
6.4.2.1 Set-up of safety inputs and start mode

			Cross-operation							
		• Results from the states of the safety elements on S11-S14, S22-S24, S31-S34 and the start signal on S42 are sent to the opposite side. They have no influence on the local safety relays.								
	Rotary switch B		 Safety relays are enabled by the results from the states of the safety elements on S11-S14, S22-S24, S31-S34 and the start signal S42 that were sent from the opposite side. 							
	0 to 4	Detection of radio start signal of	only for setting the module's own safety relay							
	5 to 9 Detection of the radio start signal together with the start signal on the IIR terminal set the module's own safety relay.									
	0,5	S11-S14, S22-S24, S31-S34	with manual start via start button on S42							
	4.6	S11-S14, S22-S24with manual start via start button on S42								
	1,6	S31-S34	with auto start							
_		S11-S14	with manual start via start button on S42							
2	2,7	S22-S24, S31-S34	with auto start							
	3,8	S11-S14, S22-S24, S31-S34	with auto start							
	4.0	S11-S14 two-hand type III A								
	4,9	S22-S24, S31-S34	with manual start via start button on S42							
		S11-S14	two-hand control type III A							
	0.5	S22-S24	with manual start via start button on S42							
		S31-S34	with auto start							
3	4.6	S11-S14	two-hand control type III A							
	1,6	S22-S24, S31-S34	with auto start							
	2,7	Rest of the positions (2, 3)	, 4, 7, 8, 9) of the rotary switch B are not assigned							
	3,8		(system error 5)							
	4.9									

- Note: In the operating modes with two-hand control, both push-buttons of the two-hand control must be released if another safety element of the UH 6900 radio-controlled safety module responds. Only after all other safety elements are free and reset, if necessary, the safety relays on the opposite side can be enabled again with the two-hand control.
- **Note:** The start button connected on S42 can be used to simulate the obligatory opening and closing of the safety elements with autostart (for ex. safety gates) after power ON of the UH 6900 radio-controlled safety module.

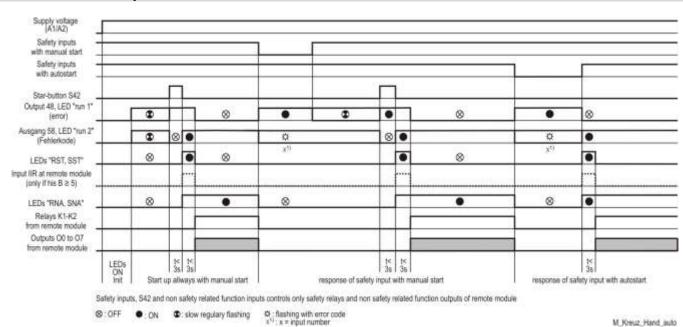
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6.4.2.2 Application examples



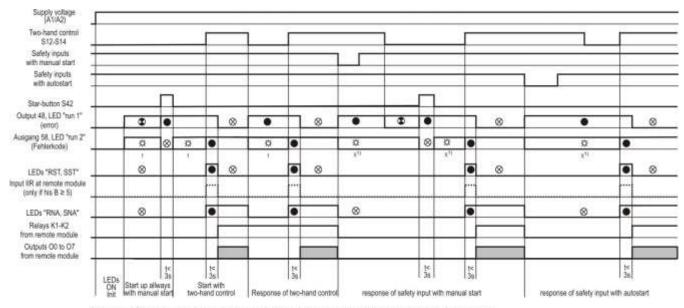
- The safety inputs on S11-S14, S22-S24 , and S31-S34 can all be equipped with a two-channel push-button or with an LC.
- Two-hand push-buttons are always connected to S11-S14.

6.4.2.3 Function diagrams



6.4.2.3.1 Cross-operation without two-hand control

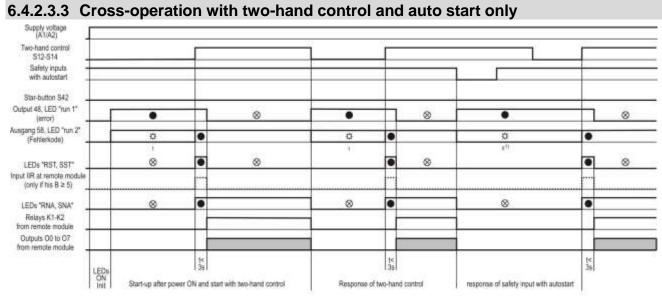
6.4.2.3.2 Cross-operation with two-hand control, manual start, and auto start



Safety inputs, S42 and non-safety related function inputs controls only safety relays and non-safety related function outputs of remote module

⊗: OFF ●: ON Φ: slow regulary flashing D: flashing with error code x¹⁰: x = input number

M_Kreuz_Zweihand_Hand_auto

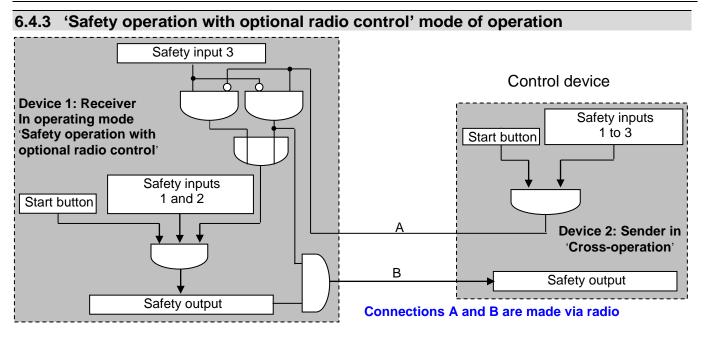


Cross-operation with two-hand control and auto start only

Safety inputs, S42 and non safety related function inputs controls only safety relays and non safety related function outputs of remote module

 $\textcircled{O::} \texttt{DFF} \quad \textcircled{O:::} \texttt{fashing} \quad \textcircled{O::::} \texttt{fashing} \quad \texttt{Wi:::} \texttt{fashing with error code} \\ x^{(i)}: x = \texttt{input number}$

M_Kreuz_Zweihand_auto



Device 1 basically works as a receiver. Device 2 basically works as an optional control device. The safety inputs 1 and 2 of the receiver module (device 1) are always enabled. They can be set for the manual or auto start types.

The state of safety input 3 switches the receiver (device 1) to one of the two operating modes below:

- Both inputs of safety input 3 are supplied with power: The receiver only works with its own safety inputs 1 and 2 In this state, a radio signal will not be decoded.
- Both inputs of safety input 3 are not supplied with power:

There must be a radio link to the control device (device 2).

In this state, the safety elements of the control device also switch off the safety relay of the receiver.

The non-safety-relevant function inputs of the control device switch the non-safety-relevant function outputs of the receiver.

The receiver sends the states of its safety relays and its non-safety-relevant function inputs to the control device, which uses them to control its safety relays and function outputs.

Devices in the '**Safety operation with optional radio control**' mode of operation are controlled by devices operating in the different variants of the '**Cross-operation**' mode of operation.



In this application mode the output contacts of the control device must not be used as safety outputs

They are only used as status feedback signals of the safety outputs of the receiver module.

SAFEMASTER W Radio controlled safety module UH 6900

• After both contacts were closed, the first contact will open:

The control device must successfully establish a radio link within the radio activation time that was pre-set with the rotary switch and the second contact of safety input 3 must also open during this time. Otherwise, the safety relays will drop out upon the lapse of this time. This wait state of the receiver module is indicated by the quick flashing of its run2 LED and its output 58.

A successful link connection is indicated by the run 1 LED and output 48 being switched off and the run 2 LED being permanently on and the output 58 being permanently enabled.

• After both contacts were open, the first contact will close:

The second contact of the safety input 3 must also close within the pre-set radio activation time; otherwise the safety relays will drop out as well.

The radio link must not be interrupted until the second contact is closed; otherwise the safety relays will drop out.

This wait state of the receiver module is indicated by the quick flashing of its run2 LED and its output 58.

• The second contact closes:

The receiver interrupts the radio link to the control device and it will then detect only its own wired safety inputs.

This condition is indicated by the run 2 LED and output 58 being switched off and the run 1 LED being permanently on and the output 48 being permanently enabled.

In this operating mode, different controllable conditions are available at the receiver module for enabling the safety relays.

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6.4.3.1 Setting the start mode and the radio activation time

	Rotary switch B: Monitoring time for radio activation									
0	1	2	3	4	5	6	7	8	9	
5 s	10 s	15 s	20 s	30 s	5 s	10 s	15 s	20 s	30 s	
[Detection of radio start signal only							t signal tog he IIR teri		

Settings of the receiver:

R	otary switch A: Setting the operating mode	
	-S14 and S22-S24 always active with manual start via S42.	
 Inputs S32, S34 supplied with power: Devices works with protective equipment on S11-S14 and S22-S24 only. No radio signal decoded. 	 Inputs S32, S34 not supplied with power: Additional reception and detection of the opposite side's signals (via radio) if the start signal from the opposite side was received within a specific time. Otherwise, the safety relays drop out. Sending of emergency stop OK and of a start signal if radio operation is OK. 	Rotary switch A
	Reset of deactivations on control device if such deactivations were triggered by the control device	4
	Reset of deactivations, that were triggered by the control device, through reset on the control device and the S42 on the receiver	5
	Reset of all deactivations through control device possible	6
Protective devices on S11-S	14 and S22-S24 always active with auto start *)	
 Inputs S32, S34 supplied with power: Devices works with protective devices on S11- S14 and S22-S24 only. No radio signal decoded. 	 Inputs S32, S34 not supplied with power: Additional reception and detection of the opposite side's signals (via radio) if the start signal from the opposite side was received within a specific time. Otherwise, the safety relays drop out. Sending of emergency stop OK and of a start signal if radio operation is OK. 	Rotary switch A
	 Reset of all deactivations through the control device. 	7
	 Reset of all deactivations through S42on the receiver after reset on control device. 	8

Rotary switch A = 1,2,3,9: Not assigned (system error 5)

*) If the receiver module is disabled while the radio control is active, for example by pressing a wireconnected emergency stop push-button, the safety elements on the control device must also be enabled again in order to enable the receiver module. This prevents that a second person switches on the machine while a person on a mobile machine equipped with a control device (for example a forklift truck) stays in the hazard zone.

Specialty with auto start settings:

If, after switching off with radio control enabled, inputs S32, S34 are supplied with power again through a wired safety element, the safety relays of the UH 6900 radio-controlled safety module are not enabled automatically. In such case, it is always the receiver module that must be enabled again by pressing the start button on S42.

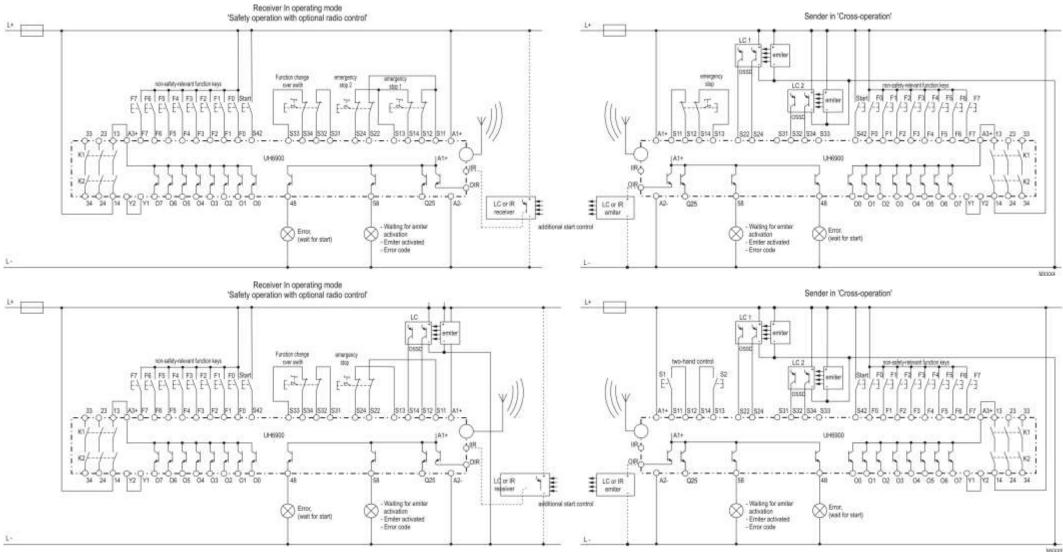


If it is intended that a person can enter the hazard zone of a machine in operation with the help of the activated radio-controlled safety module (for example one-shift operation) the machine must be running at a safe speed. The two status signals on the outputs 48 and 58 of the radio-controlled safety module UH 6900 can be used to reduce speed and activate monitoring.

To obtain reliable status information, the states of both outputs must be analysed together.

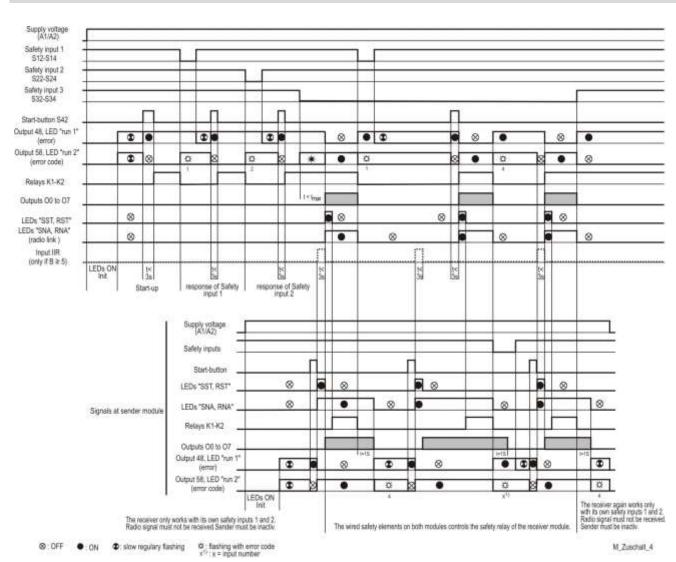
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6.4.3.2 Application examples

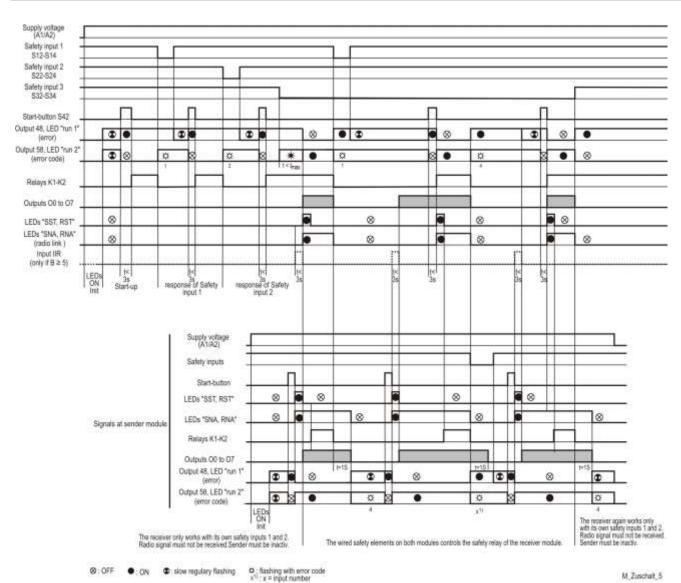


- The safety inputs on S11-S14 and S22-S24 of the receiver module in the 'Safety operation with optional receiver' operating mode can all be equipped with a two-channel push-button or with a LC of the type 4 in accordance with EN 61 496.
- For the control module ('Cross-operation' operating mode), only the operating modes without detection of the IIR input (rotary switch B≤ 5) may be used.

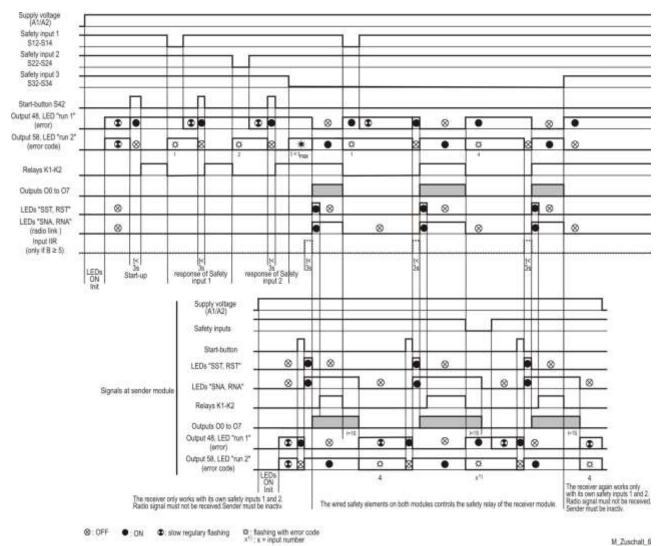
6.4.3.3 Function diagrams



6.4.3.3.1 Setting A = 4: 2 x manual start, reset of remote deactivation through control module

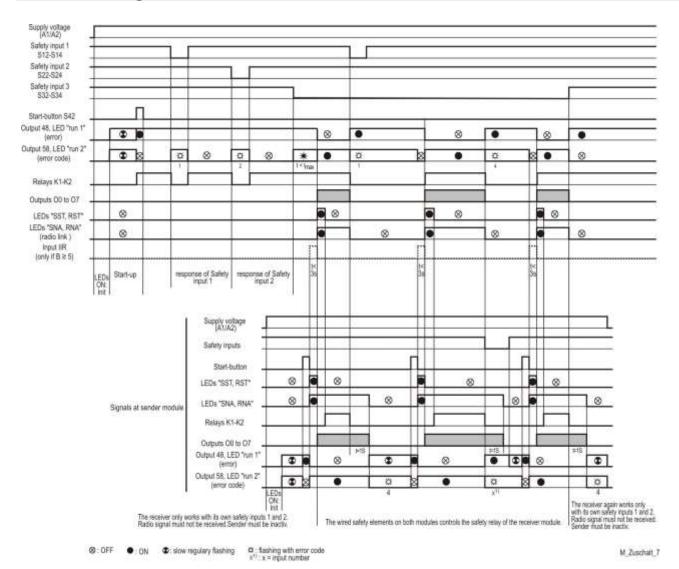


6.4.3.3.2 Setting A = 5: 2 x manual start, reset of remote deactivation with S42 after reset on control module

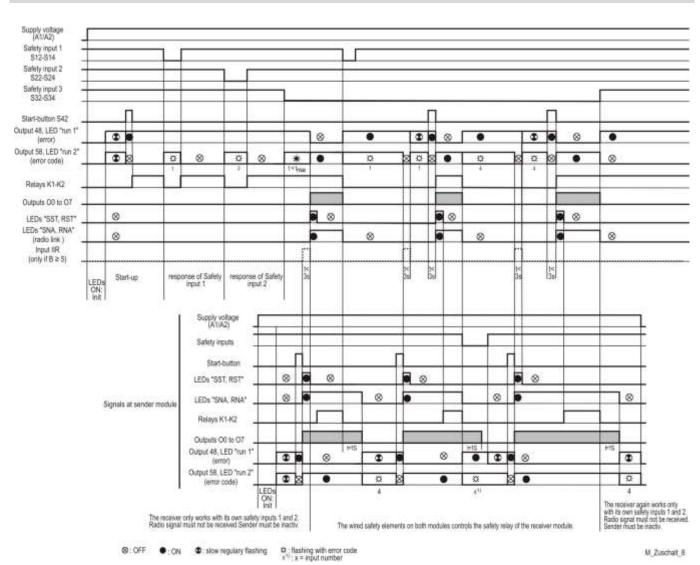


6.4.3.3.3 Setting A = 6: 2 x manual start, reset of all deactivations also on control module

M Zuschalt 6







6.4.3.3.5 Setting A = 8: 2 x auto start, reset of remote deactivation through S42 after reset on control module

7 Troubleshooting

7.1 Display and status indicators on UH 6900 radio-controlled safety module

Through three status semiconductor outputs and the LEDs on the front side of the radiocontrolled safety module, different states are indicated:

	OFF	Flashing	Continuous signal		
Output	 Radio operation, Relays K1, K2 enabled or System error if output 58 is OFF as well 	Regular slow flashing: Function error removed, waiting for start	 If output 58 and LED run 2 show a flashing code: Function error, relay K1, K2 disabled 		
	 Operation with radio, relays K1, K2 enabled System error when Run 2 with error code 	Regular slow flashing: Function error removed, waiting for start Flashing code: System error	 If output 58 and LED run 2 are OFF: Operation without radio, relays K1, K2 enabled 		
Output 58	 Operation without radio, relays K1, K2 enabled or Start button was pressed for reset or System error when Output 48 is OFF as well 	Regular slow flashing: Waiting for start after power is turned on Regular fast flashing: Waiting for radio link in optional radio operating mode Flashing code: Function error			
Yellow LED Run 2	 Operation without radio, relays K1, K2 enabled or Start button was pressed for reset or System error when Run 1 with error code 	 Regular slow flashing: Waiting for start after power is turned on Regular fast flashing: Waiting for radio link in optional radio operating mode Flashing code: Function error if Run 1 is permanently on System error if Run 1 is off or with error code 	Radio operating mode, Relays K1, K2 enabled		
Green LEDs K1, K2	Safety relays K1, K2 disabled		Safety relays K1, K2 enabled		
Yellow	Flashing: Fail	ure of radio unit or system error of	safety module		
LEDs Q1 – Q4	Fi	Indication of radio signal quality: From Q1 to Q4 Off: poor reception rom Q1 to Q4 On: excellent reception			
Green LEDs SST, RST	No radio start request		Radio start request enabled		
Green LEDs SNA, RNA	No radio signal enabled to enable the safety relays		Radio signal enabled to enable the safety relays		
Output Q25 and LED quality 25 %	Level of received radio signal above -80 dBm		No radio control or level of received radio signal below - 80 dBm		
The rer	maining yellow LEDs indicate	the detected signal of the inputs ar outputs.	nd the control signal of the		

7.2 Status and error codes

7.2.1 System errors in safety operation

A system error exists if all of the outputs (safety relays and all of the semiconductor outputs) are disabled and their related LEDs are off.

System errors are indicated by flashing codes of LED run1 and/or LED run 2, depending on the error. At the same time, LEDs 48 and 58 are OFF.

The LEDs can also show different error codes at the same time (No. = number of short flashes). In case of a system error in safety operation the LEDs Q1 and Q2 of the radio unit flash as well.

No.	Description	Notes and measures
0 (OFF)	Communication failure between the processors	 If a processor detects a system error, it indicates such error by a flashing code and interrupts communication with the other processor. The other processor will then display error 0. If both LEDs remain OFF, the device is defective and must be repaired.
5	Setting error	 The rotary switch settings for both channels do not match. Invalid setting.
6	Under- or overvoltage	 Left LED 'run 1' flashes: The supply voltage has fallen below the minimum voltage level of < 0.85 UN Right LED 'run 2' flashes: The supply voltage is too high (> 1.15 UN+ 5 % residual ripple).
7	Input failure	A short circuit has occurred on the inputs.
8	Failure on relay outputs	 If the safety relays are disabled, the feedback circuit on Y1-Y2 is not closed. (The feedback circuit must close within 50ms after disabling the relays). One of the output relays or its control is defective. Unit must be repaired.
9*)	Output failure	 If the feedback circuit on Y1-Y2 is not closed when the module is switched on the LED 'run 2' flashes indicating error 9 and LED 'run 1' indicates error 11. For one of the two channels it was detected that the required positions of the output contacts do not match.
10* ⁾	Software error	A processor detected an error in it's own routine.
11* ⁾	Matching error	 If the feedback circuit on Y1-Y2 is not closed when the module is switched on the LED 'run 2' flashes indicating error 9 and LED 'run 1' indicates error 11. It takes too long until both hardware channels match.
12	Version error	The software versions of both device components do not match. Unit must be repaired.
13	Checksum error	The program memory of a processor is defective. Unit must be repaired.
14	RAM failure	The working memory of a processor is defective. Unit must be repaired.
15	Timer failure	The timer of a processor is defective. Unit must be repaired.

*) Errors 9, 10 and 11: Try and analyse the procedure that has led to this error and pass this information to the manufacturer or supplier of the unit.

In case of questions with regard to behaviour that cannot be explained it can be beneficial if you send us a video recording of the front side that shows the flashing sequences of all LEDs in full length (minimum of 2 cycles of the LED that displays the highest error code).

7.2.2 Status indicator

As opposed to system errors, regular statuses that lead to a disabling of the safety outputs are indicated by LED 'run2' and the LED of output 58 with an error code (No.: number of flashes). As long as this error continues, the LEDs 'run 1' and 48 are permanently on and output 48 is enabled.

LED 'run 1' and output 48 flash regularly if enabling by the start button or via radio is possible again.

No	Message	Explanation
1	Deactivation through safety input 1	The safety function on S12, S14 has responded.
2	Deactivation through safety input 2	The safety function on S22, S24 has responded.
3	Deactivation through safety input 3	The safety function on S32, S34 has responded.
4	Deactivation through radio signal	The safety relay was deactivated via radio or by the other radio- controlled safety module, or the radio signal was interrupted.
5	Time-out error	Both signals of a safety input have not been enabled within 3 s. The required release of the safety relays of the other radio- controlled safety module was not properly confirmed. In the operating mode ' Safety operation with optional radio control ', the time limit for enabling or disabling the radio link after switching the contacts of safety input 3 was not met.
6	Start button pressed	Input S42 (start button) or input IIR is already supplied with power when the UH 6900 radio-controlled safety module is switched on or when the safety relay is disabled. The start button is pressed for more than 3 seconds.

8 Parameterization and diagnosis of radio features

You can adjust the radio features of the UH 6900 SAFEMASTER W module with the parameterization software 'UH 6900 Radio Board' that can be installed on any common personal computer.

The parameterization software provides the following options both for a device connected to the computer via USB or via radio:

1. Display functions:

The following parameters can be displayed but not changed:

- System codes of the devices
- Device codes of the devices
- Target device codes of the devices
- Default frequency band (433 MHz or 869 MHz)
- Received transmitter power
- 2. Change functions:

The following parameters can be displayed and changed:

- Device names of the two UH 6900 modules connected via radio
- Frequency channel
- Transmitter power
- 3. Diagnostic function:

The current state of the radio module of the device that is connected to the personal computer via USB can be displayed in a status screen and also the signal states that it can send or receive via radio.

8.1 Parameterization software 'UH 6900 Radio Board'

8.1.1 Computer HARDWARE requirements

- Operating system: Windows XP or higher
- RAM: 256 MB
- Hard disk Free disk space
 <u>></u> 30 Mbyte
- USB port: 1.1, 2.0, or 3.0
- CD ROM drive



Provide for potential equalization before connecting USB-cabel.

8.1.2 Installation of parameterization software

- Insert the installation CD;
- Wait for the installation program to request the SETUP of the software;

If it does not start automatically, open the Explorer and find and open the file **UH6900-Setup.exe**;

After the program has been installed, a window appears that prompts you to close the setup program.

If installation was successful, UH6900-Setup.exe will create an icon on your desktop.

To start the program, double-click on the icon. =>	UH6000 Radio Board
The following dialogue appears:	

🕸 License k	ey required	? 🛛
Type in license	e key, MAC address is0	0:1D:60:98:D7:B1
<u>k</u>	ОК	Cancel

A

In this dialogue, enter the license key that is supplied within a text file on CD.

8.2 RF Settings window

8.2.1 Display of radio parameters

If installation was successful and after entering the license key, the following screen will appear (and also later when you start the parameterization software directly):

Enable remote par attime termote	anveterization	of twattener band	
Local radio		Remote ra	adio board ble
Ne	184	Ese - Lagar	Take .
Discontante Aparte Al Tanta d'An Tanta D'An Tanta D'Andres	101 001 000 A (001 000 A (001 000 A A A	Spectrosen Spinstell Spinstell Spinstell Spinstell Spinstell Spinstell Spinstell Spinstell	10 40 40 1 5 5 5 1 5 5 1 5 1 5 1 5 1 5 1
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If one of the two devices of the system is connected to the computer via USB and there is no radio link to the other device this screen shows the current settings for the device: If both devices of the system are switched on and the radio link is active the settings of the target device and the received transmitter power are also displayed for both devices:

FEMASTER W	DOLD #	SAFEMASTER W	DOLD
Enable remote parameteritation dimensioner Local radio board a been stronger	Remote radio Sciend	Enable remute perameterization	Aeriste radio Scend is
Ange	No. No. Internet Internet	Note: 1 Control Contro	-
The second secon	The second secon	The second secon	
	All 		
		ma titationali m	
-			

You can save the displayed settings to a file on the computer by clicking on 'Save into file' so that you can reset your modules to their original states later, if necessary.

8.2.1.1 Device names

The device name is only used for diagnostic purposes by the user; otherwise, it has no function in the system. If you enter meaningful names for the devices, they can be easily recognized in the screens of the parameterization software.

8.2.1.2 System codes of the devices

Both devices of a SAFEMASTER W system are linked with each other by their common unique system code.

This system code is assigned by DOLD before the devices are shipped and cannot be changed. Only the two devices that have the same system code can communicate with each other.

Because the devices are designed with two channels, the system code is also stored twice in a device and the parameterization software also shows both instances of the system code.

The system code cannot be changed by the user.

8.2.1.3 Device code and target device code

In addition to the system code, the device code is also used to clearly assign the devices to each other. Therefore, the device's own device code and also the device code of the target device is stored in a device. Because the devices are designed with two channels, the device code and the target device code are also stored twice in a device and the parameterization software also shows both instances of the device codes.

The device code and the target device code cannot be changed by the user.

8.2.1.4 Frequency band

The UH 6900 devices are intended for the frequency bands of 433 MHz and 869 MHz. The parameterization software shows for which frequency band the device hardware was equipped. Because this only shows which Hardware version is installed this parameter cannot be changed by the user.

8.2.1.5 Frequency channel

The 64 radio channels in the 433 MHz frequency band and the 12 radio channels in the 869 MHz frequency band of the UH 6900 radio-controlled safety module provide a broad selection of available channels. The parameterization software can be used to set a frequency channel that is not yet used at the site. With the function 'Enable remote parameterization', any change made to the frequency channel of a device is also transferred to the other device that is connected via radio.

8.2.1.6 Transmitter power

To adjust the device's working range to the required conditions, the transmitter power can be set with the parameterization software, depending on the selected frequency channel in a range between -40 dBm (0,0001 mW) and a maximum of 10 dBm (10 mW).

8.2.1.7 Received transmitter power

The presentation of the received transmitter power of both devices in a diagram shows the quality of the radio link.

This graph is very helpful to assess the effects of a change in the transmitter power.

8.2.1.8 Software version

The software version of the radio link is shown in the device.

This information is relevant for the manufacturer only if there are any questions with regard to a reported problem.

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8.2.2 Setting of radio parameters

These settings are protected by a password that is stored in the device.

When the devices are shipped, this password is set to **0000.** The password should be changed during installation of the device and must only be disclosed to such persons who are authorized to change the settings.

For the password, numerical and also alphabetical characters are allowed.

Only the following parameters can be changed:

- Device names of the two UH 6900 modules connected via radio
- Frequency channel
- Transmitter power

Changes to the parameters of the devices can only be made if their registers are unlocked by clicking on the '**Register unlock request**' button and the subsequent entering of a valid password.

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If the 'Enable remote parameterization' box is ticked, the target device may also be set via radio (but only if the password is known and the register is unlocked).



- To change the frequency channel you should use the 'Enable remote parameterization' function. With this function, any change of the radio channel is transferred to both devices immediately.
- As long as the registers are locked, all settings are shown with a grey background.
- Once a register has been successfully unlocked, you can change the parameters which are then shown with a white background.

SAFEMASTER W Radio controlled safety module UH 6900

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Changes to parameters become valid immediately but at first, they are only saved in th working memory of the devices.

Therefore, when the first change is made the **Program flash** ..., button lights up. This is to indicate that the changes must be saved by clicking on this button.

(!)

By enabling the remote parameterization or by unlocking the registers, the system will enter into a safe state in which the machine release paths are deactivated immediately through the safety relays. A restart of the machine is possible only after the steps listed below have been taken in the order mentioned:

- Program the flash memories of the devices on which this is indicated by the blue markings.
- Lock the registers.
- Disable the remote parameterization function.

(!)

If the transmitter power is reduced too much through the remote parameterization function of the target device it may be that the target device cannot be reached any longer and that it becomes necessary to parameterize the target device locally via the USB interface, or by turning off and on the target device, in order to increase the transmitter power to an adequate level.

SAFEMASTER W Radio controlled safety module UH 6900

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As long as the changes have not been saved to the flash memory (Program flash ..., button with a blue background), the system may be reset to its original state by simply turning it off and on again.

Too many changes using the remote parameterization function within a short period of time (for example, by the mouse wheel) may lead to transmission errors that result in a locking of the registers of both devices although the settings have not been saved in the flash memory yet. In such case, you have to repeat the remote parameterization and the unlocking of the registers on both devices in order to save the settings in the flash memory.

8.2.2.1 Device names

The device name is only used for diagnostic purposes by the user; otherwise, it has no function in the system. By assigning a meaningful device name, the devices can be recognized more easily in the screens of the parameterization software.

8.2.2.2.1 List of available frequencies in the 433 MHz band

8.2.2.2 Frequency channel

The 64 radio channels in the 433 MHz frequency band and the 12 radio channels in the 869 MHz frequency band of the UH 6900 radio-controlled safety module provide a broad selection of available channels.

By enabling the '**Enable remote parameterization**' function, any frequency channel change made on one device is also transferred to the other device that is connected via radio.

Frequency 433 MHz, distance between channels: 0.025 MHz.							
Channel	Frequency MHz	Channel	Frequency MHz	Channel	Frequency MHz	Channe I	Frequenc y MHz
01	433.100	17	433.500	33	433.900 ⁽²	49	434.300 ⁽²
02	433.125	18	433.525	34	433.925 ^{(1, (2}	50	434.325 ⁽²
03	433.150	19	433.550	35	433.950 ⁽²	51	434.350 ⁽²
04	433.175	20	433.575 ⁽¹	36	433.975 ^{(1, (2}	52	434.375 ⁽²
05	433.200	21	433.600	37	434.000 ⁽²	53	434.400 ⁽²
06	433.225	22	433.625 ⁽¹	38	434.025 ^{(1, (2}	54	434.425 ⁽²
07	433.250	23	433.650	39	434.050 ⁽²	55	434.450 ⁽²
08	433.275	24	433.675 ⁽¹	40	434.075 ⁽²	56	434.475 ⁽²
09	433.300	25	433.700	41	434.100 ⁽²	57	434.500 ⁽²
10	433.325	26	433.725 ⁽¹	42	434.125 ⁽²	58	434.525 ⁽²
11	433.350	27	433.750	43	434.150 ⁽²	59	434.550 ⁽²
12	433.375	28	433.775 ⁽¹	44	434.175 ⁽²	60	434.575 ⁽²
13	433.400	29	433.800 ⁽²	45	434.200 ⁽²	61	434.600 ⁽²
14	433.425	30	433.825 ^{(1, (2}	46	434.225 ⁽²	62	434.625 ⁽²
15	433.450	31	433.850 ⁽²	47	434.250 ⁽²	63	434.650 ⁽²
16	433.475	32	433.875 ^{(1, (2}	48	434.275 ⁽²	64	434.675 ⁽²

⁽¹: List of channels that can be used in Denmark

⁽²: List of channels that can be used in Singapore

With a transmitter power of > 0 dBm only the channels 40 to 64 are available.



If the frequency channel is changed to an area that does not allow the set transmitter power, the parameterization software will reduce the transmitter power to the maximum value that is allowed.

8.2.2.2.2 List of available frequencies in the 869 MHz band

Frequency 869 MHz, distance between channels: 0.025 MHz.

Channel	Frequency MHz										
1	869.7125	3	869.7625	5	869.8125	7	869.8625	9	869.9125	11	869.9625
2	869.7375	4	869.7875	6	869.8375	8	869.8875	10	869.9375	12	869.9875

8.2.2.3 Transmitter power

To adjust the device's working range to the required conditions, the transmitter power can be set with the parameterization software depending on the selected frequency channel in a range between -40 dBm (0,0001 mW) and a maximum of 10 dBm (10 mW).



In the 433 MHz frequency band, the full range of 64 frequency channels can be set for a transmitter power of up to 0 dBm (1 mW) only. With a power of > 0 dBm (1 mW to 10 mW) only the channels 40 to 64 are available.

In the 869 MHz frequency band, the transmitter power can only be set to a maximum of 7 dBm (5 mW).

The adjustable transmit power refers to the power transmitted at the connector of the device (values in green). The radiated power of the antenna can be different to that depending on the used antenna and cable.

Typically the antenna cable has an attenuation of 0.3dB/m. A normal size 1/4-wave antenna has 0dB, while a compressed 1/4-wave shows around 3dB attenuation. In contrast a 1/2-wave antenna exhibits a gain of 5dB.

For compensation of the attenuation the transmit power at the connector can be increased (value in yellow). If a 1/2-wave antenna is used the transmit power must be decreased accordingly.



When you change the transmitter power, the parameterization software allows only entries that are allowed for the set radio channel. For example, transmitter powers of over 1 mW (0 dBm) are allowed only if the frequency channel is set to \ge 40.

If the 'Enable remote parameterization' box is ticked, the effects of this change in the transmitter power of a device are immediately shown in the 'Received transmitter power' diagram of the other device.

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Setting of transmitter power for channel numbers < 40 (433 MHz band)

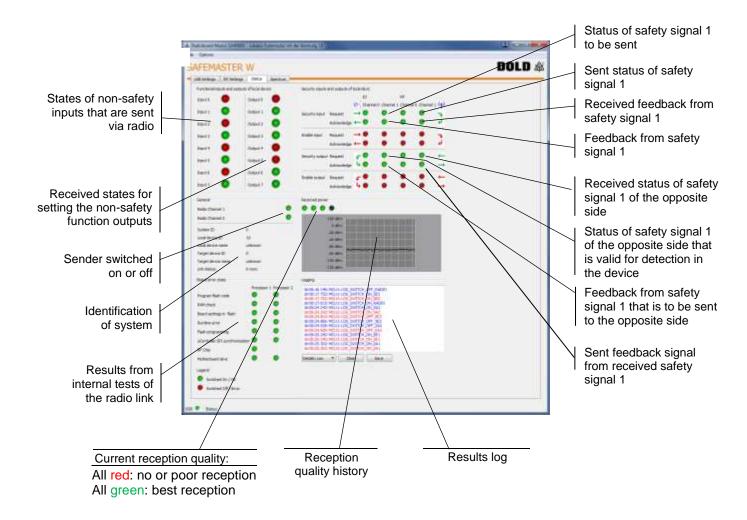
SAFEMASTER W Radio controlled safety module UH 6900

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Setting of transmitter power for channel numbers ≥ 40 (433 MHz band)

8.3 STATUS screen (diagnostic function)

This screen shows the current state of the radio module of the device that is connected to the personal computer via USB and the signal states that it can send or receive via radio.





It is also possible to open a second instance of the parameterization software or to display the status of another device at the same time via a second USB port.

8.4 Spectrum screen (diagnotic function)

This window can be used to get a quick overview about the current environment i.e. which channels are already occupied or still free.

The radio board will be set into receiver mode where all channels of the frequency range will be scanned and the received power measured.

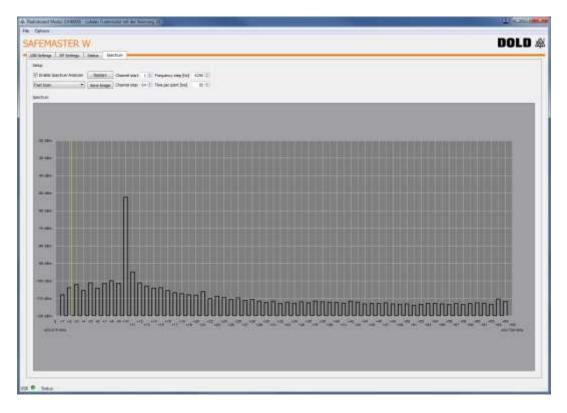


When activating the spectrum analyzer function the system will enter into a safe state in which the machine release paths are deactivated immediately through the saftey relays. That's because the radio module scans all available channels and therefore a safe communication with the normally connected module via a unique channel is not possible anymore.

Using the mode "Fast Scan" all channels defined by Channel Start and Channel Stop will be scanned as fast as possible. Each channel will be sampled at the precices channel frequency

SAFEMASTER W Radio controlled safety module UH 6900

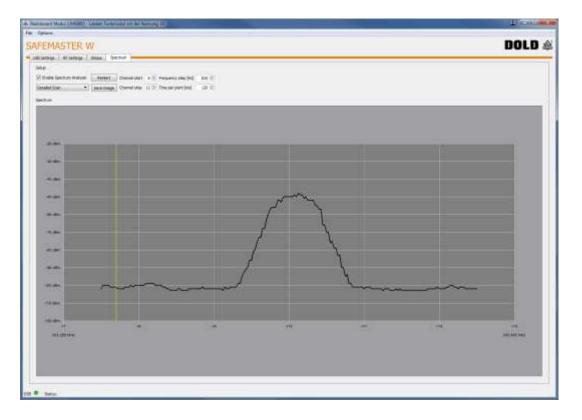
and in a distance defined by Frequency Step below and above the middle frequency. The default values don't have to be modified for this measurement.



In this example channel 10 is obviously occupied. Measurement values below (80-90)dBm are normally noise or they are caused by wide band transmitter polluting their neighboring channels.

Using the "Detailed Scan" mode the channels defined by Channel Start and Channel Stop will be scanned and dis[played with a higer resolution. Resolution is defined by the parameter Frequency step.

Due to lower speed of measurement this mode should only be used when observing a small number of channels.



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9 Technical data

Radio	
Conformity:	ETS 300 220
Carrier frequency:	UHF, frequency modulated (FM)
Frequencies:	64 channels in the 433 MHz frequency band
riequencies.	12 channels in the 869 MHz frequency band
Frequency range (license free):	433.1000 434.6750 MHz in the 433 MHz frequency band
	869.7125 869.9875 MHz in the 869 MHz frequency band
Maximum HF transmitter power:	
	7 dBm (5 mW) in the 869 MHz frequency band
	Integrated antenna
Minimum HF transmitter power:	-40 dBm (0.0001 mW)
Range:	approx. 250m in industrial environment150 m ¹⁾
	approx. 800 m in open area
Antenna:	$1/4$ wave antenna, impedance 50 Ω , plug in as accessory
Sensitivity:	< -100 dBm
•	g on the ambient conditions of the antennas (roof
construction, metal walls etc.)	5
Power supply:	
Nominal voltage U _N :	DC 24 V
Voltage range:	0.85 to 1.15 U _N at max. 5 % residual ripple
Nominal consumption:	max. 160 mA (Semiconductor outputs without load)
•	
	S33:approx. DC 23 V pulse, average value approx. 7 V at U_N
Control voltage on 48, 58, OIR, Q2	
Control current on S12, S14, S22,	
F0, F1, F2, F3, I	
	on S12, S14, S22, S24, S32, S34, S42,
F0, F1, F2, F3, I	
	al on S12, S14, S22, S24, S32, S34, S42
F0, F1, F2, F3, I	
Max. input current on S12, S14, S2	
F0, F1, F2, F3, I	
Fusing:	Internal with PTC
Max. difference time between inpu	t signals of one function
Emergency stop, LC, safety gate	-
Two-hand:	500 ms
Safety outputs: Contacts:	
UH 6900.03: 3 NO contacts	
	1 NC contact(NC contact must be used as an indicator
contact only!)	The contact indicator indicator
Contact type: Relay, positive	quided
Nominal output voltage:	AC 250 V
The way of a summer to be a Que due	DC: see arc limit curve under resistive load
Thermal current Ith (see Quadrat	tic total current limit curve) 5 A
Switching capacity to AC 15	
NO contact:	AC 3 A / 230 V IEC/EN 60 947-5-1
NC contact: To DC 13:	AC 1 A / 230 V IEC/EN 60 947-5-1 DC 2 A / 24 V IEC/EN 60 947-5-1
DC rs. DC switching capacity:	DC 2 A / 24 V IEC/EN 60 947-5-1 DC 8 A / 24 V at 0.1 Hz IEC/EN 60 947-5-1
	(two contacts in a row)

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Switching of low loads: Minimum switching voltage: Minimum switching current: Minimum switching capacity:

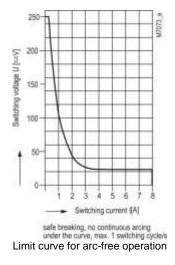
Electrical life

to AC 15 at 2 A, AC 230 V: Allowed switching frequency: Please also refer to section 4.10 Disturbance protection

Short circuit strength

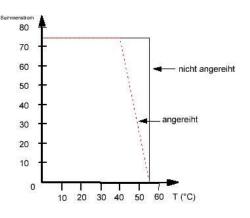
max. fuse rating: Mechanical life:

Typical nick-up times at UM



100,000 switching cycles IEC/EN 60 947-5-1 max. 1200 switching cycles / h

> 6 A gL IEC/EN 60 947-5-1 10 x 10⁶ switching cycles



Quadratic total current limit curve

max. 2.5 s no operating mode with automatic start	Ready for start after power is turned on: Automatic start:
max. 1 s ²⁾ max. 1.1 s ²⁾	Operating mode 'Full safety operation' Manual start: Automatic restart:
max. 650 ms ²⁾ max. 650 ms ²⁾	Operating mode 'Cross-operation' Manual start: Automatic restart:
ional radio control [,] max. 70 ms max. 80 ms	Operating modes 'Safety operation with optio S32, S34 supplied with power: Manual start: Automatic restart:
trol device): max. 70 ms max. 700 ms ²⁾	Reset through S42 on control device: Reset through S42 not supplied with power: Reset through S42 not control device: Reset through auto start on control device
testion of the UD input the delay time of the	2) For the start antions with additional data

²⁾ For the start options with additional detection of the IIR input, the delay time of the safety element connected to this input must be added to the pick-up times.

Deactivation time (response time)

S12-S14, S22-S24, S32-S34:	max. 30 ms
Deactivation via radio (S12-S14, S22-S24, S32-S34 of 2nd device):	max. 200 ms
Passive deactivation in case of interrupted radio signal:	max. 500 ms

> 5 V

> 5 mA

> 25 mW

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Semiconductor outputs Outputs (terminals 48, 58, O0 to O7, OIR, Q25): Transistor outputs, plus switching Nominal output voltage (A3+): DC 24 V Output voltage at U_N: min. DC 23 V, max. 100 mA continuous current max. 400 mA for 0.5 s internal short circuit, over-temperature and overload protection for inductive loads, arrange the necessary safety measures Minimum operating current: min. 1 mA **Residual current:** min. 0.1 mA **General Data** Nominal operating mode: Continuous operation Temperature range: -25 °. 55 °C -40 ° . +80 °C Storage temperature: Operating altitude: ≤2000 m Clearance and creepage distance Rated impulse voltage / pollution degree: (contact/contact) 6 kV/2 IEC 60 664-1 (circuit/contact) 4 kV/2 IEC 60 664-1 III IEC 60 664-1 Overvoltage category IEC/EN 61 326-3-1. IEC/EN 62 061 EMC: Limit value class B EN 55 011 Interference suppression: **Protection category:** Enclosure: IP 40 IEC/EN 60 529 Terminals: IP 20 IEC/EN 60 529 Enclosure: Thermoplastic with V0 behaviour according to UL Subject 94 Vibration resistance Test Fc: EN 60068-2-6 Amplitude, constant 0.075mm 10 - 57Hz Acceleration, constant 1g: 57 - 150 Hz Shock resistance test Ea EN 60068-2-27 Acceleration: 10g 16 ms Impulse length: Number of shocks per direction and axis: 1000 **Climate resistance:** 25 / 055 / 04 IEC/EN 60068-1 **Terminal designation:** In accordance with EN 50 005 max. terminal cross-section: 1 x 2,5 mm² stranded wire with sleeve or 1 x 2.5 mm² solid or 2 x 1 mm² stranded wire with sleeve or 2 x 1 mm² solid DIN 46 228-1/-2/-3/-4 0.25 mm² stranded wire with sleeve or min. terminal cross-section: 0.2 mm² solid DIN 46 228-1/-2/-3/-4 removable terminal blocks, with cage clamp terminals Wire fixing: or screw terminals Profile DIN rail IEC/EN 60 715 Quick mounting: Net weight: 380 g **Dimensions:** Width x height x depth: 45 x 107 x 121 mm

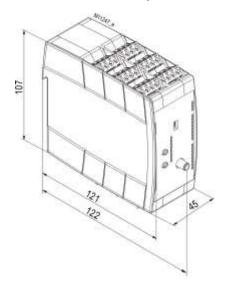
9.1 Safety related data

EN ISO 13849-1:			
Category	4		
PL:	e		
MTTF _d :	187,6	a (years)	
DC _{avg} :	97,6	%	
d _{op} :	365	days/a	
h _{op} :	24	h/day	
t _{cycle} :	3600	s/cycle	

IEC/EN 62061, IEC/EN 61508, IEC/EN 61511:				
SIL CL:	3	IEC/EN 62061		
SIL	3	IEC/EN 61508,		
		IEC/EN 61511		
HFT *)	1			
DCavg:	97,6	%		
PFH _D :	3,6E-10	h ⁻¹		
PFD _{avg} :	1,2E-4	Low Demand Mode		
*) HFT = Hardware Fault Tolerance				

9.2 Dimension drawing

Radio-controlled safety module UH 6900



45 mm

10 Order information

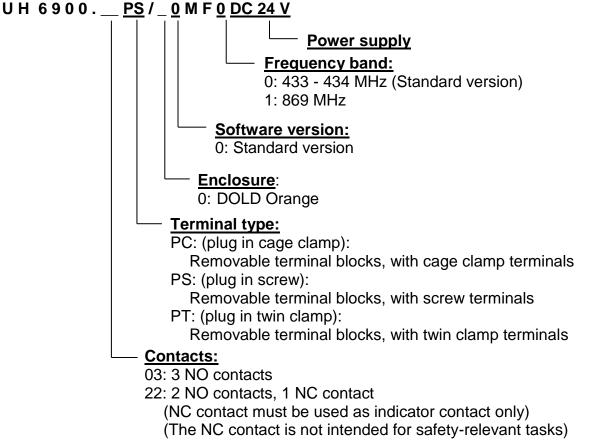
10.1 Wireless Safety System

10.1.1 Standard type

Width:

UH 6900.03 PS / 00MF0 DV24Volt				
Article number:	0067213			
Safety output:	3 NO contacts			
Nominal voltage:	DC 24 V			

10.1.2 Example for ordering variations



The scope of delivery includes a radio-controlled safety system UH 6900 and a CD that includes the parameterization software and this user manual.

10.2 Accessories

	description	part no.
CD configuration software radio controlled safety module	ZB6900/100	0067641
Antenna 1/2 wave, 433 - 434 MHz BNC	ZB6900/040	0067254
Antenna 1/4 wave, 433 - 434 MHz SMA	ZB6900/041	0067255
Antenna 1/2 wave, 869 MHz SMA	ZB6900/050	0067256
Extension cable for aerial(2 m) with through hole connector	ZB6900/042	0067257
Extension cable for aerial (5 m) with through hole connector	ZB6900/043	0067258
Adaptor BNC-SMA	ZB6900/044	0067642
Connector SMA 90° angular	ZB6900/045	0067675
Photoelectric switch for additional start control	ZB6900/060	0067259
1 Set of connection cable for photoelectric switch (2m)	ZB6900/061	0067260

11 Maintenance and care

User-friendly maintenance

- Indicator LEDs for diagnosis
- The settings of the radio parameters can be saved in a settings file from which they can be retrieved again.

Regular checks

In addition to the tests during commissioning and set up, the following test must be carried out in regular intervals and after each maintenance job (once a year at minimum):

- Checking of all safety functions
- User-friendliness, for example easy operation of all connected operating elements
- Response times of the SAFEMASTER W system
- Wiring between the UH 6900 radio-controlled safety modules and the machine circuit
- Proper functioning of active deactivation via radio
- Proper functioning of passive deactivation in case of an interrupted radio signal
- Checking of antenna for: correct connection, undamaged antenna shell, cleanliness and check that it is free of oxidation

Safety function requirements on the device		Intervals for regular checking of safety functions	
In accordance with EN ISO 13849-1	3 or 4	Once a month	
	PL d, category 3	Once a year	
In accordance with	SIL 3, HFT = 1	Once a month	
IEC/EN 62061 IEC/EN 61508	SIL 2, HFT = 1	Once a year	
In accordance with EN 61511	SIL 3	Once a year	

12 Disclaimer and warranty

The safety instructions listed in the manual MUST be observed.

The applications listed in this manual are examples only and each individual case must be reviewed by the user in its own responsibility. Their applicability must therefore be evaluated on a case-by-case basis.

Please be aware that our SAFEMASTER W is a radio-controlled system that could be influenced by external radio signals. In the case of external interferences the availability of the system could be impaired by sudden disconnection, without, however, impairing the safety of men and machine.

We are not liable for influences of this kind.

We recommend setting up an internal frequency plan in order to avoid double usage of frequency channels.

13

CE declaration of conformity						
	De	EG-Konformitätserklärung Declaration of Conformity Déclaration de conformité européenne				
Hersteller: Manufacturer: Fabricant:	781 Bre	Dold & Söhne KG 20 Furtwangen gstraße 18 rmany				
Produktbezeichnung Product description: Designation du produit:	: SAFEMASTER V	W Funk Sicherheitsmodul Radio controlled safety module Module de sécurité à réception rad	UH6900.xxYY/00MFz mit xx = 03, 22, YY = PS, PC, PT dio und z = 0, 1			
Optional/optionnel :			/60 /69			
The indicated product i	s in conformance with t	en Vorschriften folgender Europ he regulations of the following europe ns des directives européennes:	päischer Richtlinien überein: an directives:			
Maschinenrichtlinie Machinery directive:/ Direc		2006/42/EG				
EMV-Richtlinie: EMC-Directive:/Directives	-CEM:	2014/30/EU				
RED-Richtlinie: RED-directive: / Dirctives-	RED:	2014/53/EU				
Prüfgrundlagen: Basis of Testing : Lignes de contrôle:	EN ISO 13849-1:2015 EN 60204-1:2006 + A1:2009 + AC:2010 (in extra EN 62061:2005 + AC:2010 + A1:2013 + A2 :201 EN 61000-6-1:2007 EN 61000-6-3:2007 + A1:2011 EN 55011:2009 EN 62368-1:2014 + AC:2015 (RED-Article 3.1a) EN 301 489-1 V2.1.0 (RED-Article 3.1b) EN 300 220-1 V2.4.1 (RED-Article 3.2)		EN ISO 13850:2015 EN 50178:1997 IEC 61508 Parts 1-7:2010 EN 61000-6-2:2005 EN 61000-6-4:2007 + A1:2011 EN 62311:2008 (RED-Article 3.1a) EN 301 489-2 V2.1.0 (RED-Article 3.1b) EN 300 220-2 V2.4.1 (RED-Article 3.2)			
Richtlinie wurde bes Consistency of a production	scheinigt durch: a sample with the marked or	des bezeichneten Produktes mit oduct in accordance to the above machines di directives machine susmentionnées a été cert	der oben genannten Maschinen-			
		TÜV Rheinland Industrie Alboinstrasse 56 12103 Berlin	e Service GmbH			
Nummer der benanr Number of certification offi	iten Stelle : ice:/ Numéro de l'organisme	NB0035 notifié				
	Nummer der Bescheinigung: Certification number: / Numéro de certificat		Ausstelldatum: 17.11.2016 Date of issue: / Date de délivrance			
Richtlinie wurde bes Consistency of a production	scheinigt durch: a sample with the marked pr	des bezeichneten Produktes mit oduct in accordance to the above RED-direct directives RED susmentionnées a été certifié	ive has been certified by			
		CETECOM ICT Service Untertuerkheimer-Str. 6- 66117 Saarbrücken				
Nummer der benanr Number of certification offi	nten Stelle : ice:/ Numéro de l'organisme	682 notifié				
	Nummer der Bescheinigung: Certification number: / Numéro de certificat		Ausstelldatum: 14.11.2016 Date of issue: / Date de délivrance			

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EG-Konformitätserklärung Declaration of Conformity Déclaration de conformité européenne



Für die Zusammenstellung der technischen Unterlagen ist bevollmächtigt: For the compilation of technical documents is authorized:/ Pour la composition des documents techniques est autorisé

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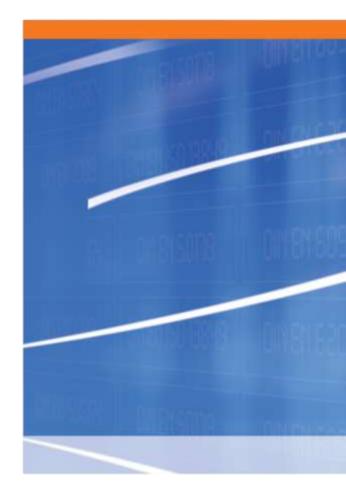
Ort, Datum: Furtwangen, 19.12.2016 Place, Date: / Lieu, date:

Diese Original - Erklärung bescheinigt die Übereinstimmung mit den genannten Richtlinien, beinhaltet jedoch keine Zusicherung von Eigenschaften. Die Sicherheitshinweise der Produktdokumentation sind zu beachten.

This original declaration confirms the conformity of the mentioned directives but does not comprise any guarantee of the product characteristics. The safety directives of the product documentation are to be considered.

Cette déclaration originale certific la conformité des directives nommées mais ne comprend aucune garantie des caractéristiques du produit. Les directives de sécurité de la documentation du produit sont à considérer.

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